



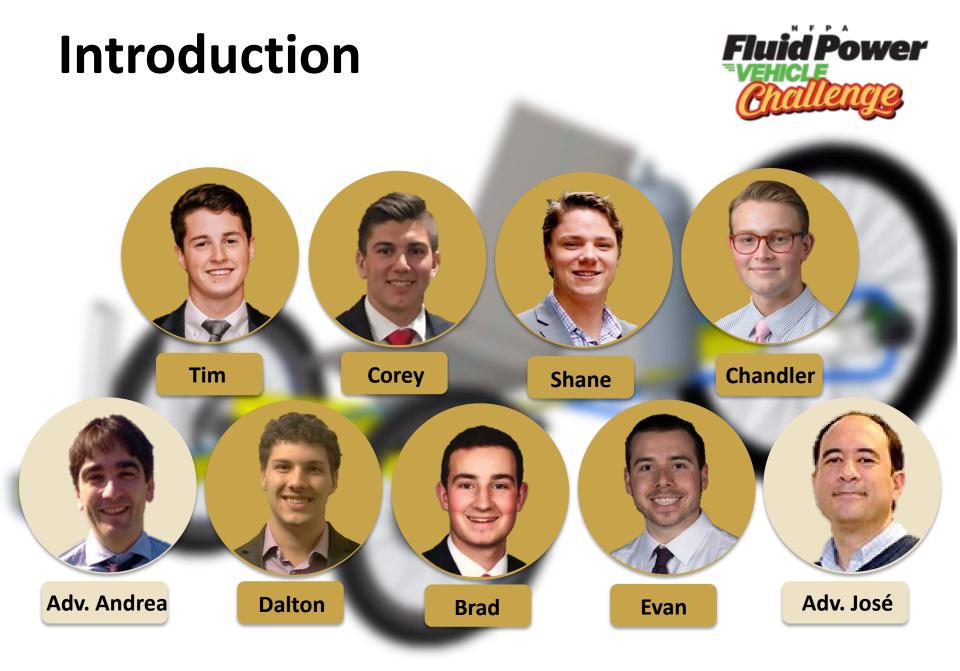
NFPA Education and Technology Foundation FINAL PRESENTATION Purdue University Andrea Vacca & José Garcia-Bravo April 11, 2019



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Problem Statement & Design Objectives

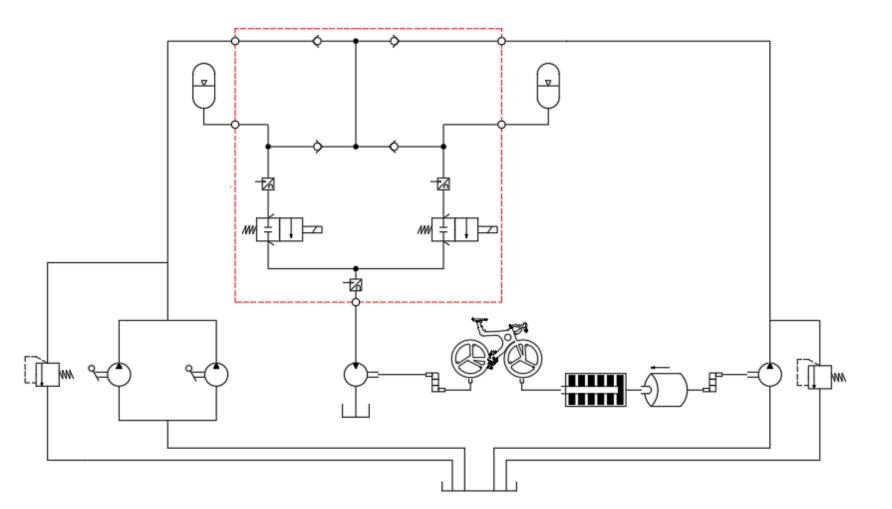


There is a need to design and build a human powered vehicle that uses fluid power to transfer and store energy using novel approaches and innovative technology.

- Minimize overall weight
- Properly size components
- Maximize human comfort
- Implement necessary safety features
- Charge accumulators and use pump to maintain pressure

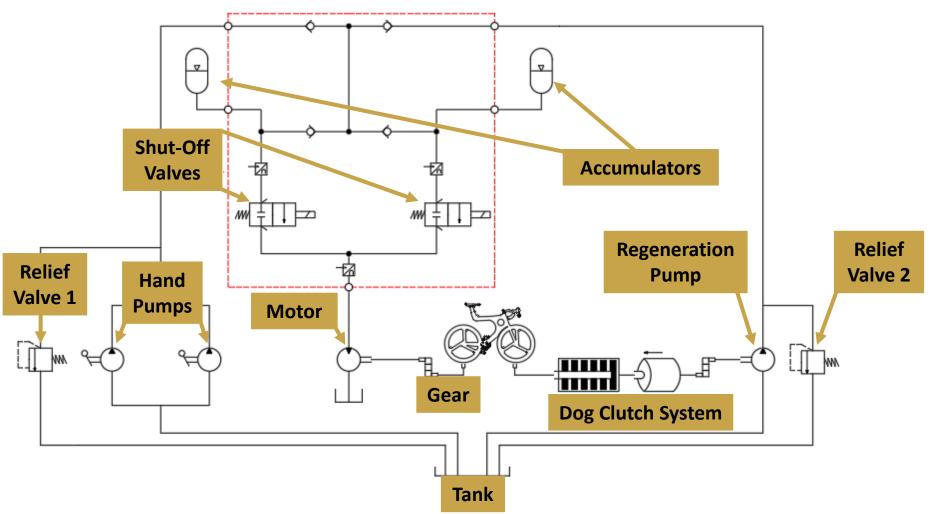
Hydraulic Circuit Overview





HC: Component Layout

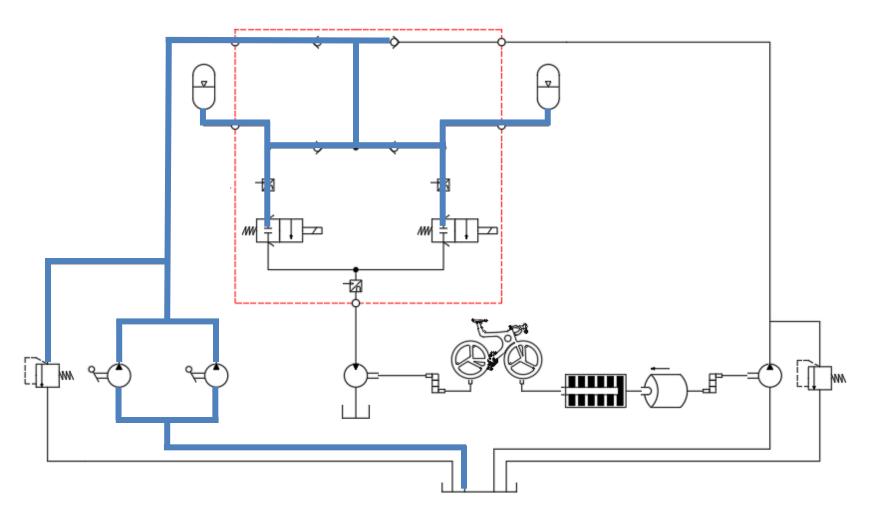




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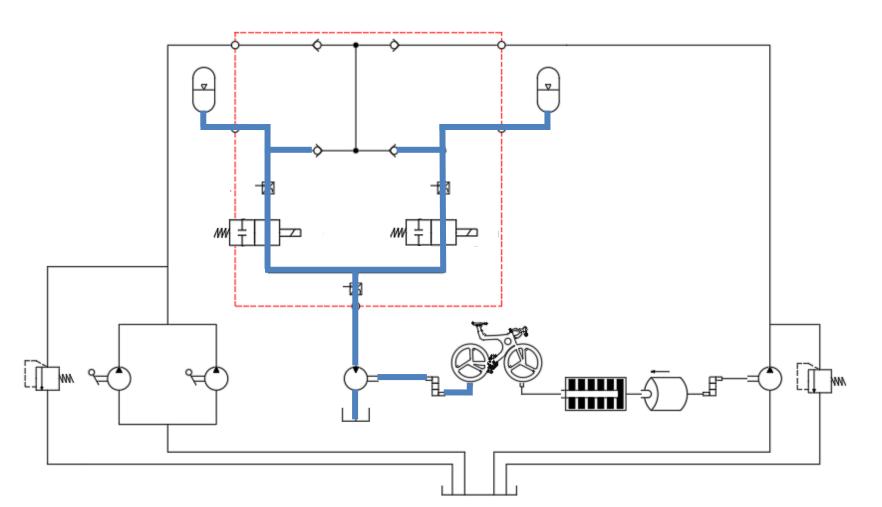
HC: Charging Mode





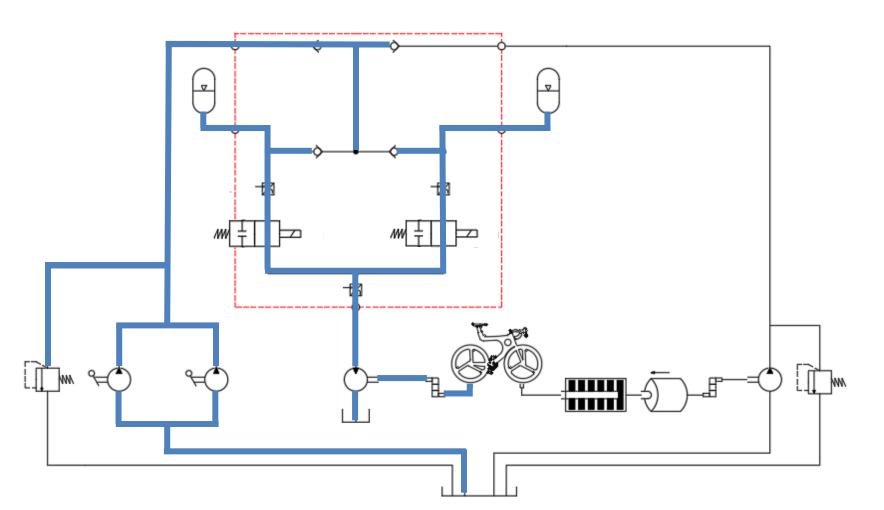
HC: Boost Mode





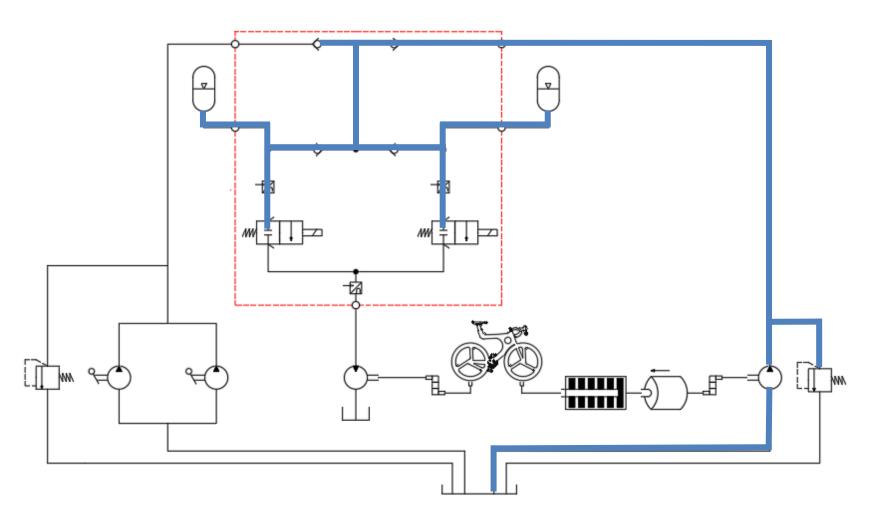
HC: Pump Mode





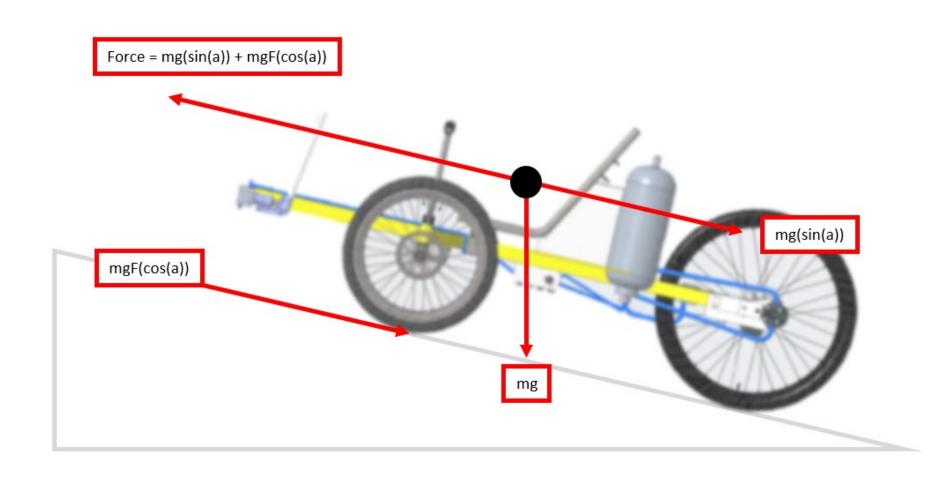
HC: Regen Mode







Sizing the Circuit



Hydraulic Input Design Matrix



| | | | Dr | turn RC | WINB Le | Press |
|--------------------|---------------|--------------------------|----|---------|---------|-------|
| | | Stability | S | - | S | |
| | Performance | Versatility | S | - | S | |
| ŋ | | Power | S | + | + | |
| Selection Criteria | | Weight | S | - | + | |
| Crit | Efficiency | Aerodynamics | S | S | S | |
| u u | | Smoothness | S | - | - | |
| ctic | | Component Routing | S | - | + | |
| <u>e</u> | Manufacturing | Component Space | S | - | + | |
| Ň | | Complexity | S | - | + | |
| | Missellaneous | Aesthetics | S | + | - | |
| | Miscellaneous | Ergonomics | S | S | - | |
| | | | | | | |
| | | SCORE | | 2 | 5 | |

Hydraulic Pumping Design Matrix



| | | | 01 | atum Di | Dal FOOT | Purit Pur | INP PUT | np atic pur |
|------------|---------------|-----------------------|----|---------|----------|-----------|---------|-------------|
| | Performance | Stability | S | + | S | S | + | |
| <u>a</u> . | Performance | Weight | S | + | + | + | + | |
| Criteria | Efficiency | Rideability | S | + | + | + | S | |
| Ċ | Efficiency | Component Routing | S | S | S | S | + | |
| | | Component Space | S | S | S | + | + | |
| cti | Manufacturing | Cost of Modifications | S | + | + | + | S | |
| Selection | | Modification Time | S | + | + | S | S | |
| | Miscellaneous | Aesthetics | S | + | + | + | S | |
| | wiscellaneous | Innovative | S | + | - | + | S | |
| | | | | | | | | - |

| SCORE | 7 | 5 | 6 | 4 |
|-------|---|---|---|---|

Overall Hydraulic Bill of Material (BOM)



| Accumulators | Hand Pump | Motor | Regeneration Pump |
|--------------|---------------|-------------|----------------------|
| | | | |
| 2 x 1.3 USG | 7.5 cc/stroke | 3.12 cc/rev | 7.54 cc/rev |
| MAX Pressu | re: 3000 psi | MAX Pressu | ure: 3600 psi |

Frame Design Matrix

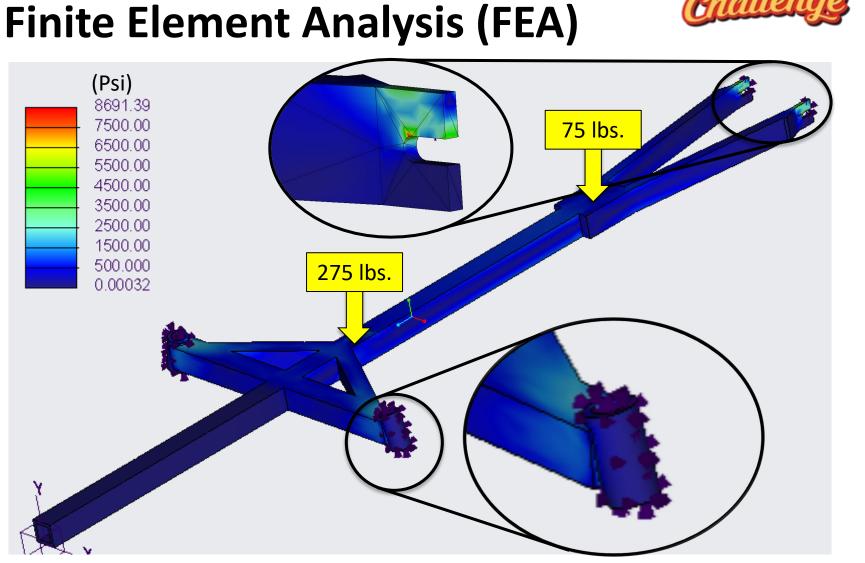


| | | | 5 | atum | He N | ountain | Bike Bike N | onowheel |
|--------------------|---------------|-----------------------|---|------|------|---------|-------------------|----------|
| | | Stability | S | + | S | S | - | |
| | Performance | Versatility | S | S | + | + | - | |
| | | Weight | S | - | + | + | + | |
| <u>a</u> . | | Rideability | S | + | S | + | S | |
| ter | Efficiency | Rolling Resistance | S | S | + | + | + | |
| Cri | 편 Efficiency | Component Routing | S | + | + | + | - | |
| L L | | Aerodynamics | S | + | S | + | - | |
| Selection Criteria | | Component Space | S | + | + | + | S | |
| e e | Manufacturing | Cost of Modifications | S | - | S | S | + | |
| Š | Manufacturing | Modification Time | S | S | S | S | - | |
| | | Weldability | S | + | S | + | - | |
| | Missellenes | Aesthetics | S | S | + | + | + | |
| | Miscellaneous | Ergonomics | S | + | + | + | + | |
| | | | | | | | | |
| | | SCORE | | 7 | 7 | 10 | 5 | |





Square 6061 Aluminum **Aluminum Plates** Tubing 10 feet^2 ~ 10 feet

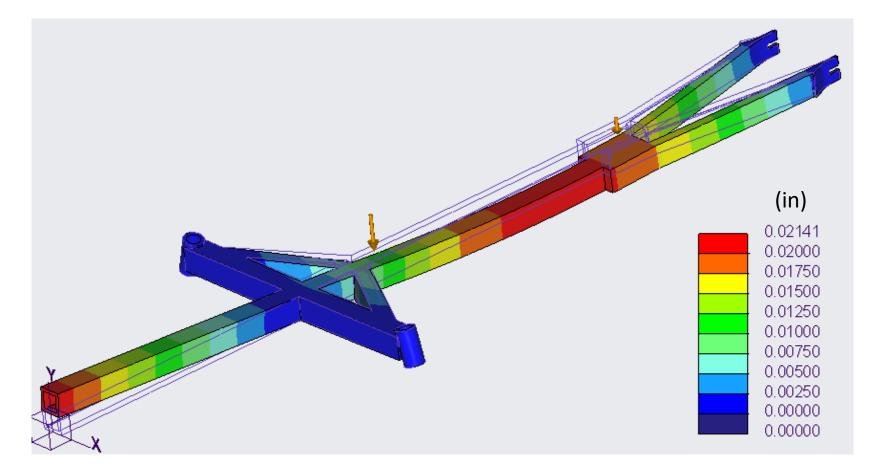


Frame

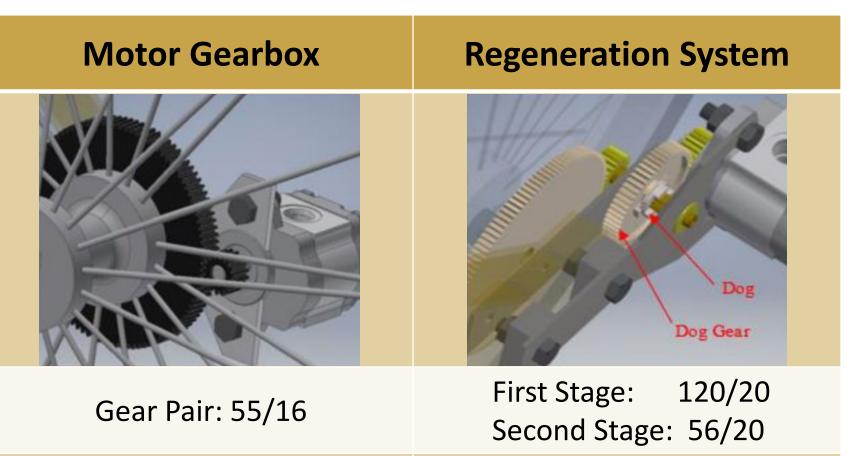
Fluid Power

Frame Deformation





Mechanical Components BOM



Gear Ratio: 3.45:1

Total Gear Ratio: 16.8:1

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Fluid Power

Electronics Design Matrix

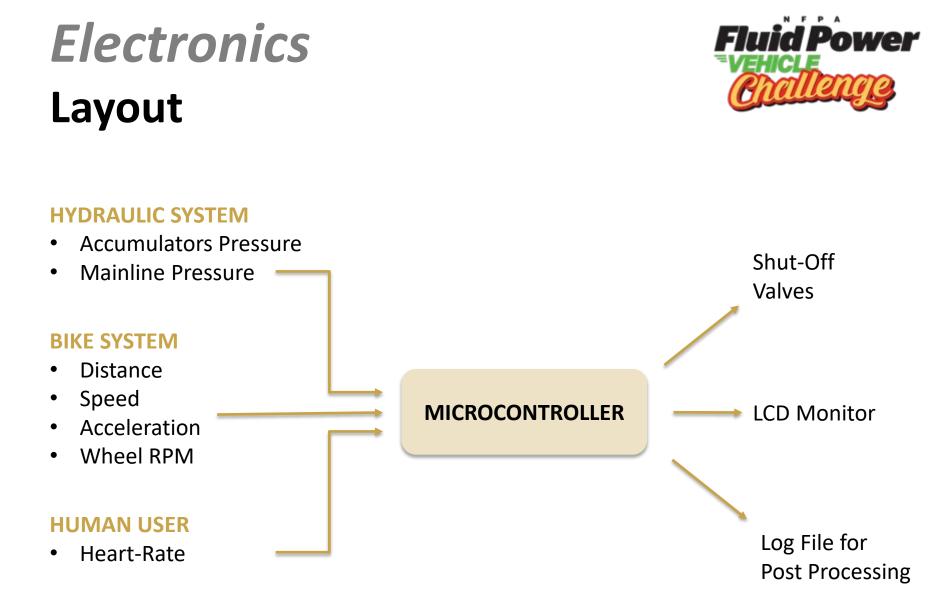


| | | | 05 | atum R? | ssperry In | pi leloule | 510 ⁴ | 200 BC | ard Bone Black |
|-----------|---------------|-----------------|----|---------|------------|---------------|------------------|--------|----------------|
| | Performance | Clock Speed | S | S | + | + | + | - | |
| <u>a</u> | renormance | Cores | S | + | + | + | + | - | |
| eri | | GPIO | S | + | S | S | - | + | |
| Criteria | Efficiency | GPIO Voltage | S | + | - | - | - | + | |
| u (| | Power | S | - | - | - | S | - | |
| ctic | Connectivity | Bluetooth | S | + | S | - | S | - | |
| Selection | Connectivity | Wifi | S | S | + | - | S | - | |
| Ň | Miscellaneous | Memory | S | + | + | + | + | S | |
| | | Onboard Storage | S | - | S | S | S | + | |
| | | | | | | | | | |
| | | SCORE | | 5 | 4 | 3 | 3 | 3 | |

Electronics BOM



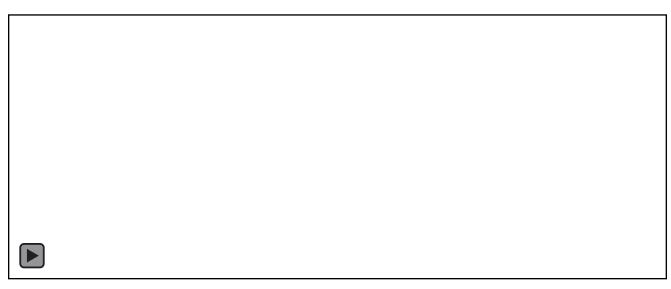
| Speed | User | Central Unit | Supply |
|----------------|---------------------|---------------------------------------|--------|
| | | | |
| Hall Sensor | Heartrate Sensor | Raspberry Pi & Miscellaneous Items | Power |



Vehicle Design Summary

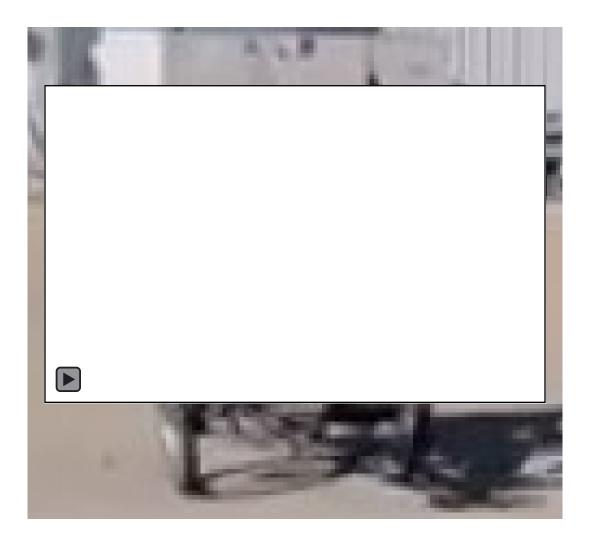


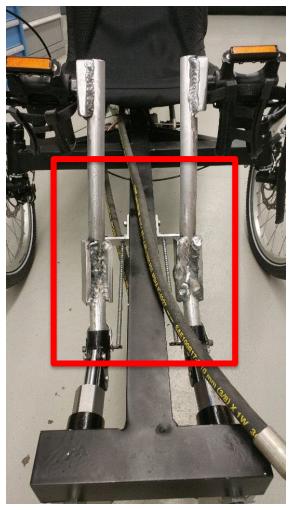
| Criteria | Constraints |
|-------------|---|
| Lightweight | Less than 210 lbs. |
| Strong | Support a human rider with all components |
| Stable | 3 wheels |
| Compact | Enough room for all components |



Testing & Changes Made







Conclusion



- Power
 - Foot pumps
 - 2 x 1.3 gal. accumulators
- Gearboxes:
 - Motor: 55/16 pair (3.45:1 ratio)
 - Regeneration: 120/20 pair (first stage), 56/20 pair (second stage) [16.8:1 Total ratio]
- Electronic Controls
 - Increase versatility, improve functionality
 - Easy transition between modes
 - Real-time feedback

Lessons Learned



- Supply Chain
 - Make sure parts are easily obtainable and ordered well in advance
- Hydraulic Nuances
 - Talk to professionals and don't be afraid to ask questions
 - Never "fake it till you make it"
- Time Management
 - Leave room in the project timeline for mistakes and problems
- Scope Creep
 - There's no such thing as scope creep only scope gallop
 - Focus on the need and *look into* the "nice to haves" later

Thoughts?











