

N F P A

Fluid Power

VEHICLE

Challenge



NFPA
Education and
Technology
Foundation

Final Presentation
Murray State University
Staff Advisor – Roger Riquelme
Industry Mentor - Joshua Scarbrough
04/07/2021



MURRAY STATE
UNIVERSITY

Team Members

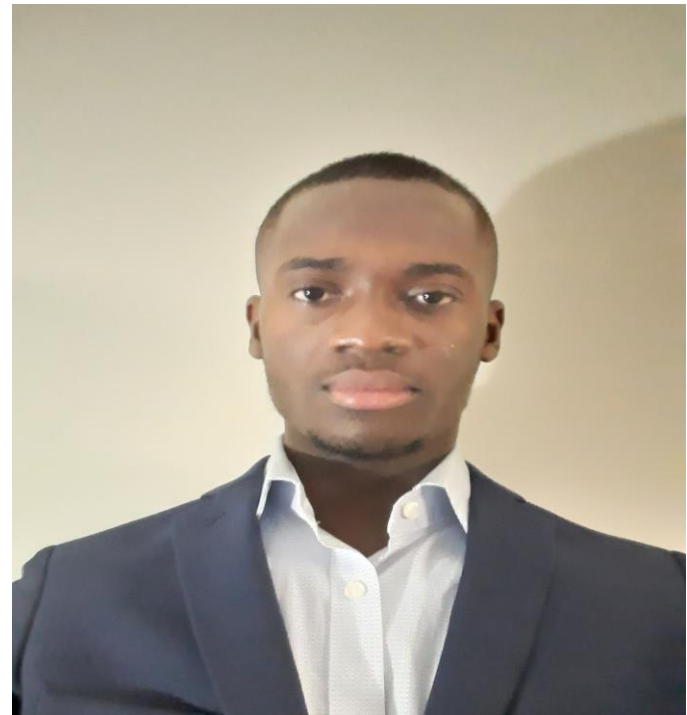


Roger Riquelme
Team Advisor
Instructor Murray

Team Members



Nate Heady
ElectroMechanical
Senior



Dami Ogunjimi
Electromechanical Engineering Tech
Sophomore

Team Members



Carson Elliott
ElectroMechanical
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Problem Statement



To design a hydraulic bike that is driven solely on human power through the use of fluid power components in a reasonably safe manner.



Design Goals

- Redesign steering of the vehicle
- Optimize the accumulator circuit
- Regear the Human Powered circuit for a Higher Pressure/Lower Flow Rate system
- Integrate and properly utilize a pneumatic system
- Redesign power input
- Integrate Electronics
- Minimize custom fabrication

Winning Tactics: Sprint Race



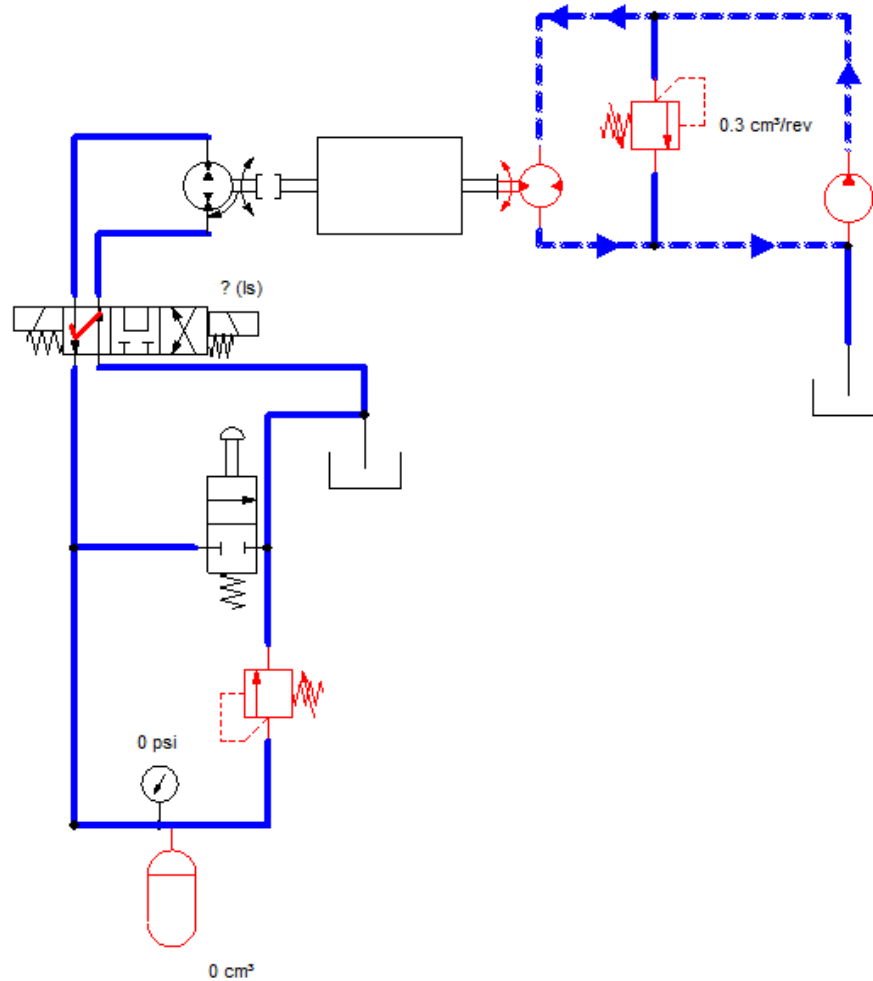
- Make efficient use of our stored potential energy
 - Minimize coasting
 - Use all energy before crossing the finish line
- Control our acceleration via gear ratios and timing
 - Multi Speed gear box
- Allow for max flow rate with the D03

Winning Tactics: Efficiency and Lap Race

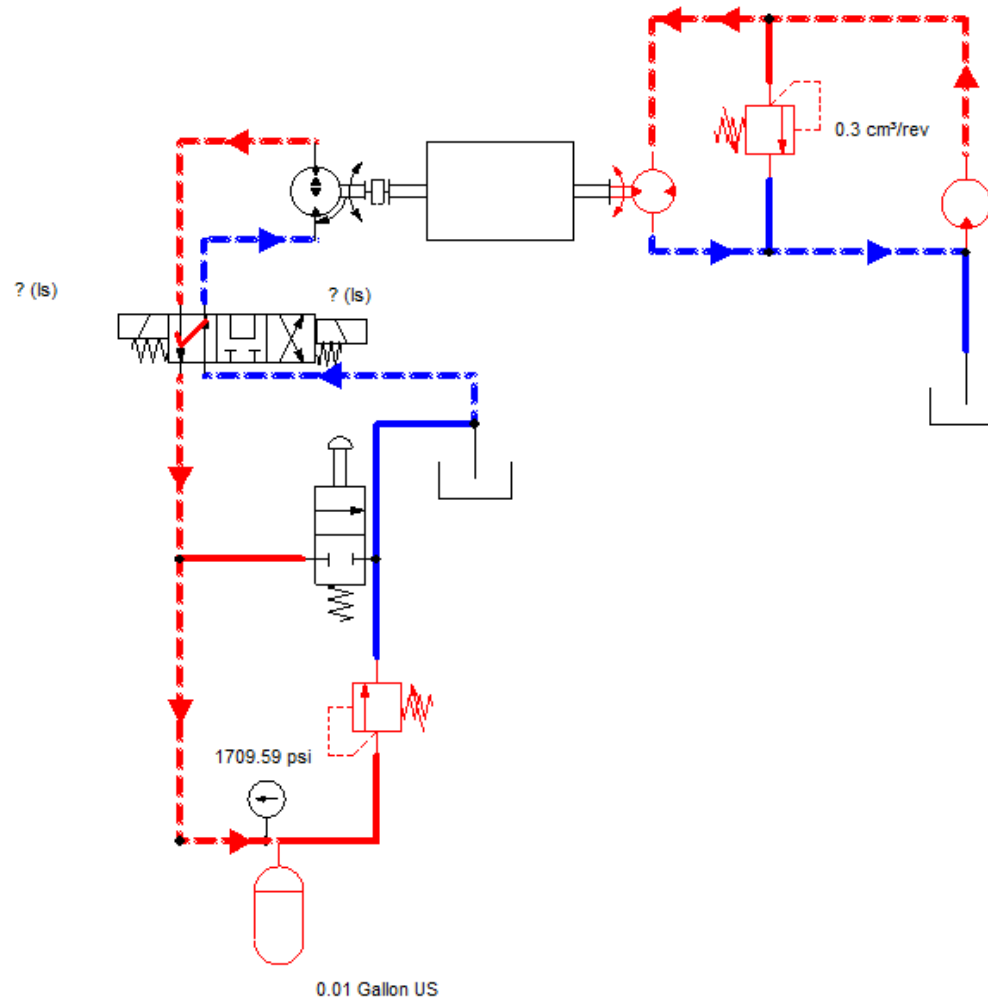


- Keep the system pressure above 1700 psi to maximize efficiency
- Make use of our 2 speed gearbox and clutch system
 - Disengaging the clutch allows us to coast after discharging the fluid in the accumulator
 - The 2 speed gearbox allows us to easily charge up potential energy after the initial discharged
 - Freewheel (ratchet) on the human powered side prevents pedals from turning while coasting

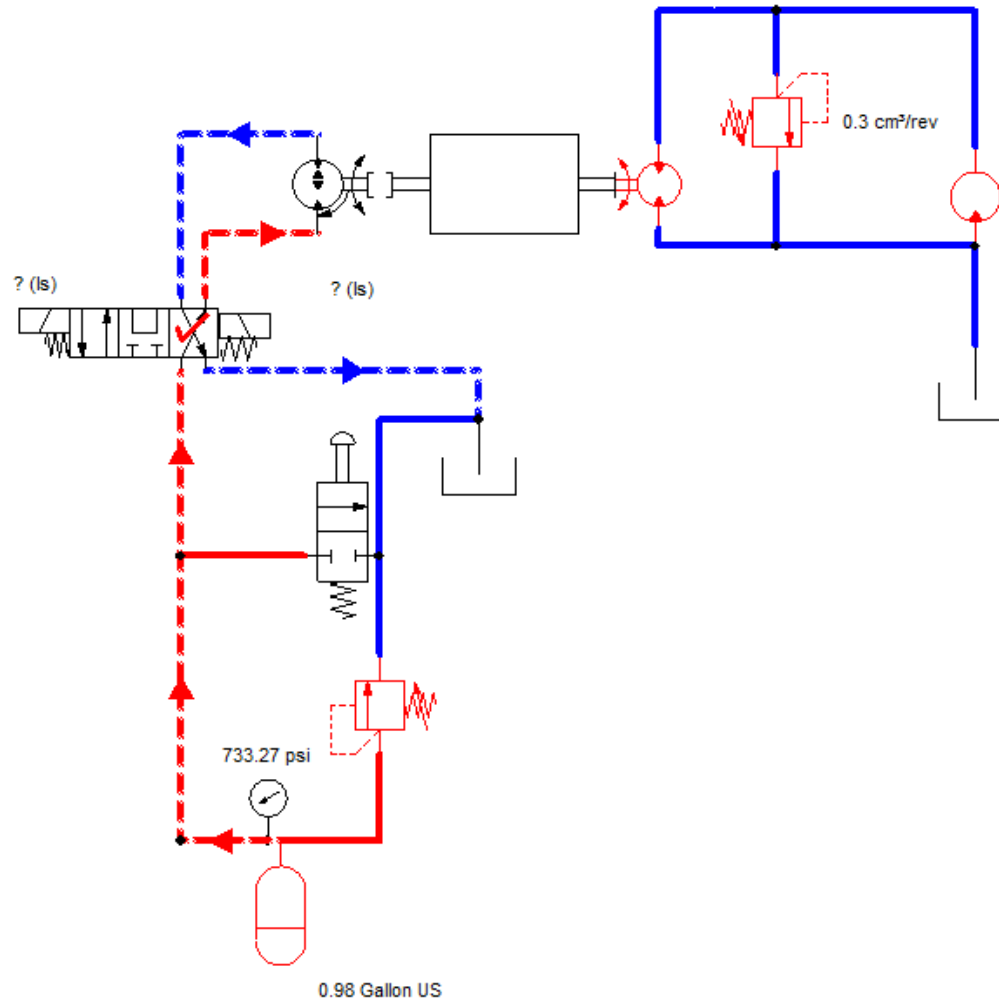
Human Powered



Regeneration



Accumulator Discharge



Power Input

Chain and Sprocket

- Much more efficient
- Easy to use
- Allows for a variety of gear ratios
- Easier to obtain parts
- Cheaper to buy components

Components Choices

- Our system was operating at a flow rate that was approaching the flow rate capacity of cartridge valves
- We opted for a more traditional C top D03



Motor/Pump Choice

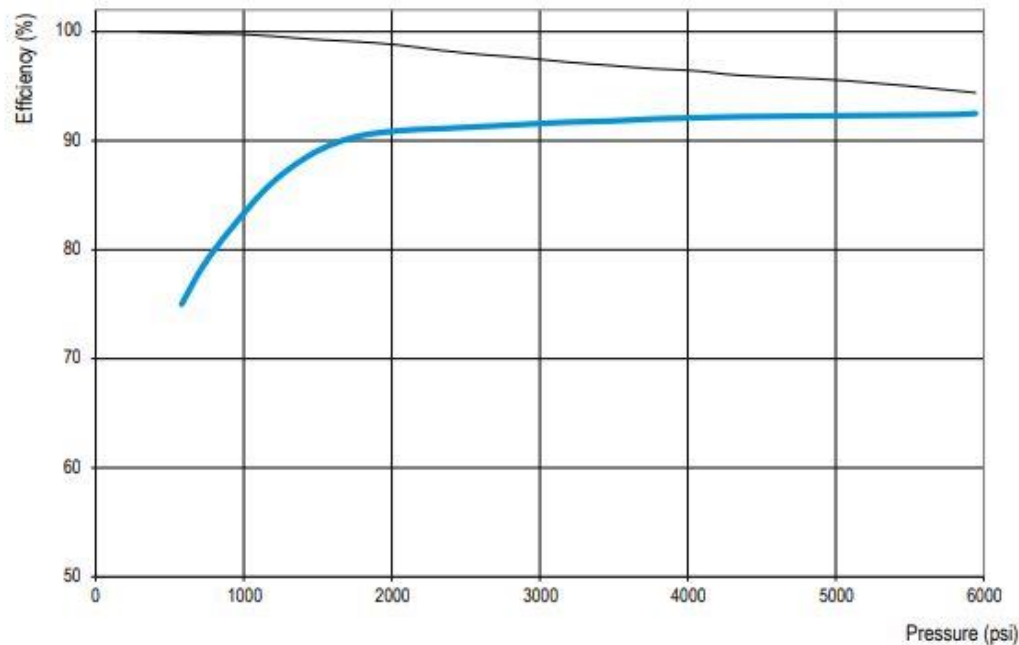
- We have three piston motors/pumps
- One Hydro Leduc micropump
 - Powered by rider
 - High volumetric efficiency
 - Compact design
- Two Hydro Leduc bent axis pump/motors
 - Mounted on Regeneration and Human powered circuits
 - Very high efficiency (greater than 90% above 1700 psi)

HydroLeduc Efficiency



EFFICIENCY OF M / MA / MSI SERIES MOTORS

N motor = 1000 rpm
ISO46 fluid at 77° F (25°C)

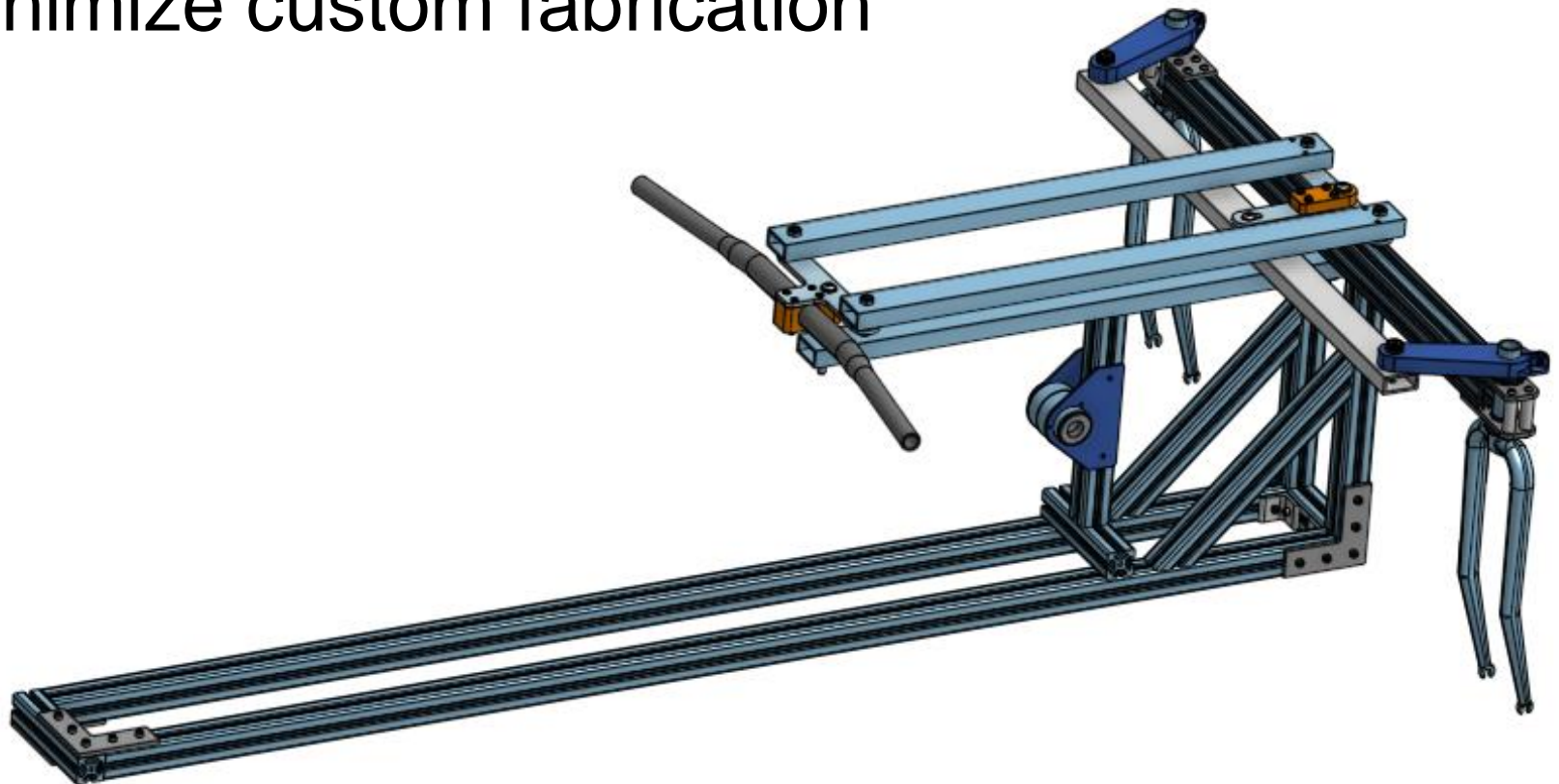


— Global efficiency
— Volumetric efficiency

This graph is given as an indication only.
For further information, please contact our Technical Service.

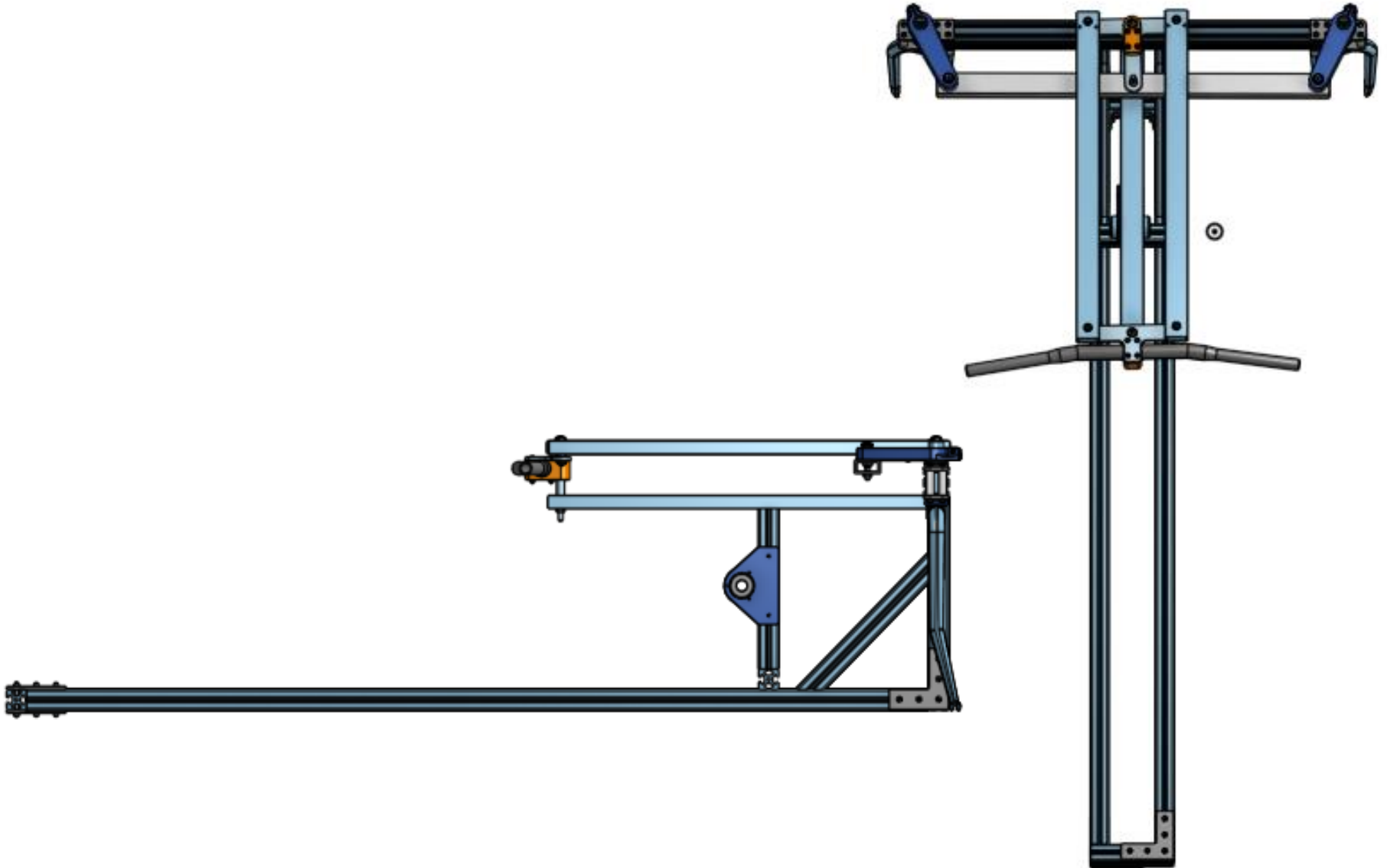
Frame

- 80-20 Aluminium
- Stability
- Minimize custom fabrication



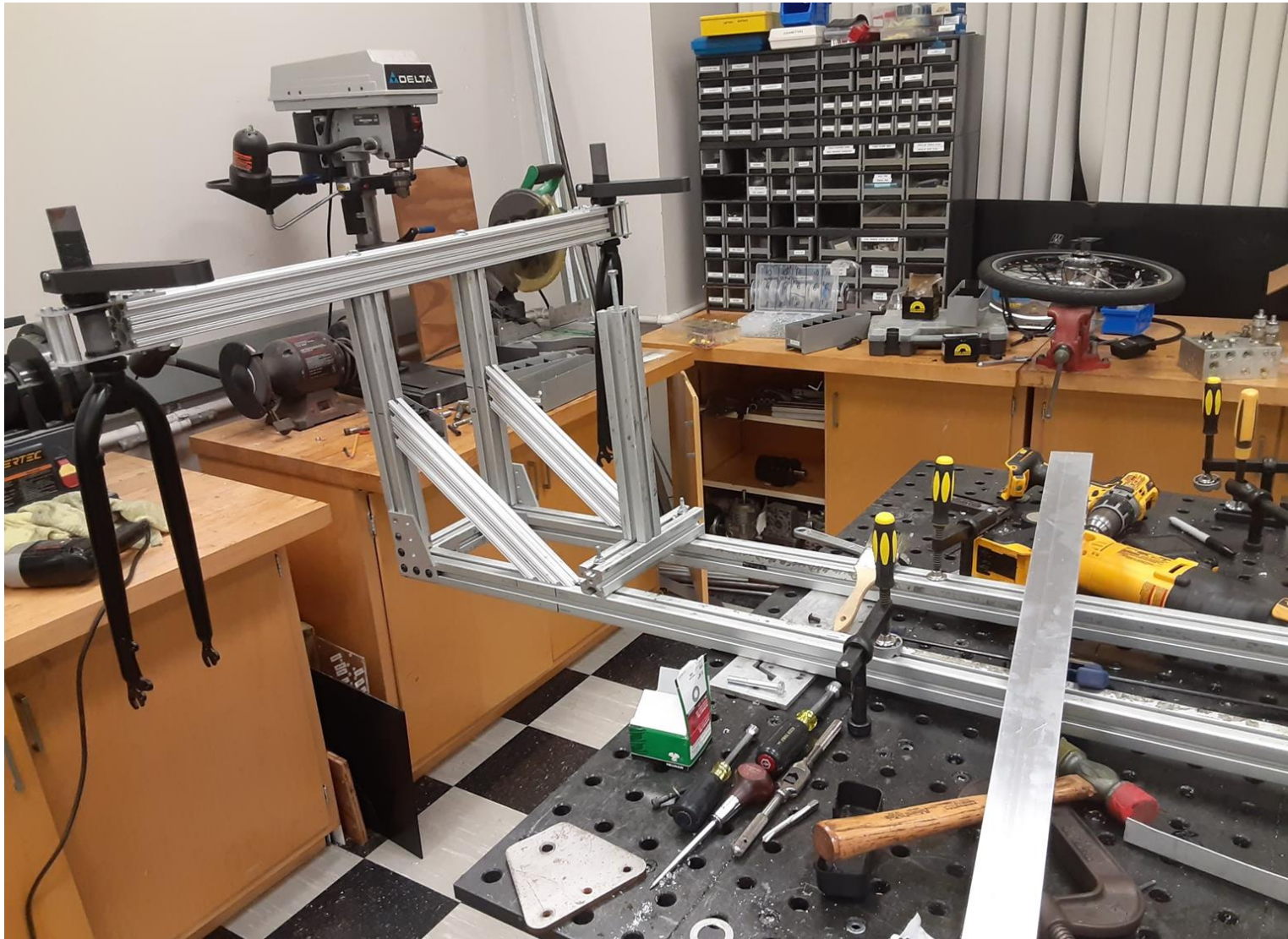
Frame

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Frame Construction

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Manifold Mounting



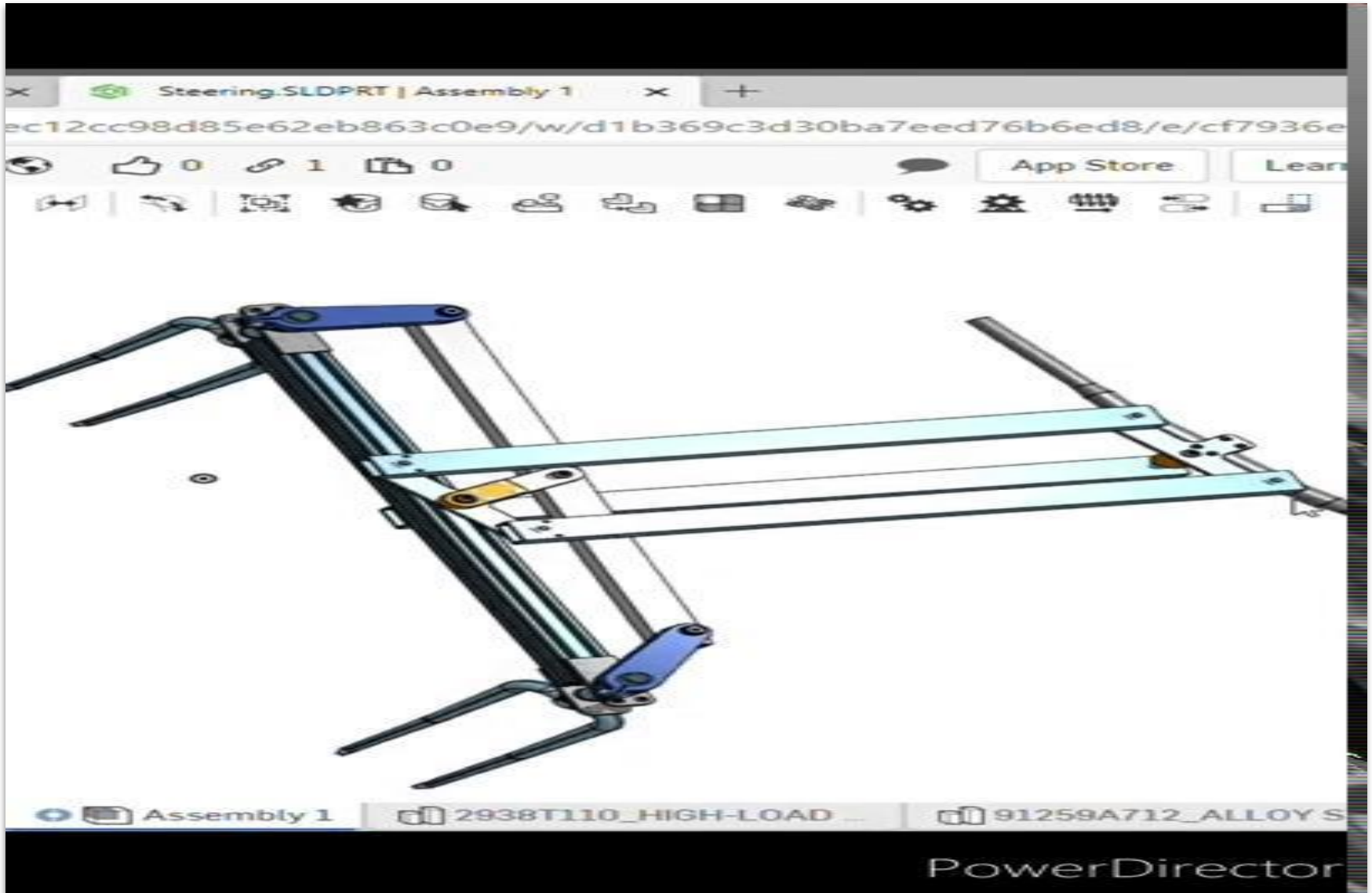
Wheel Mounting



The frame as it stands now



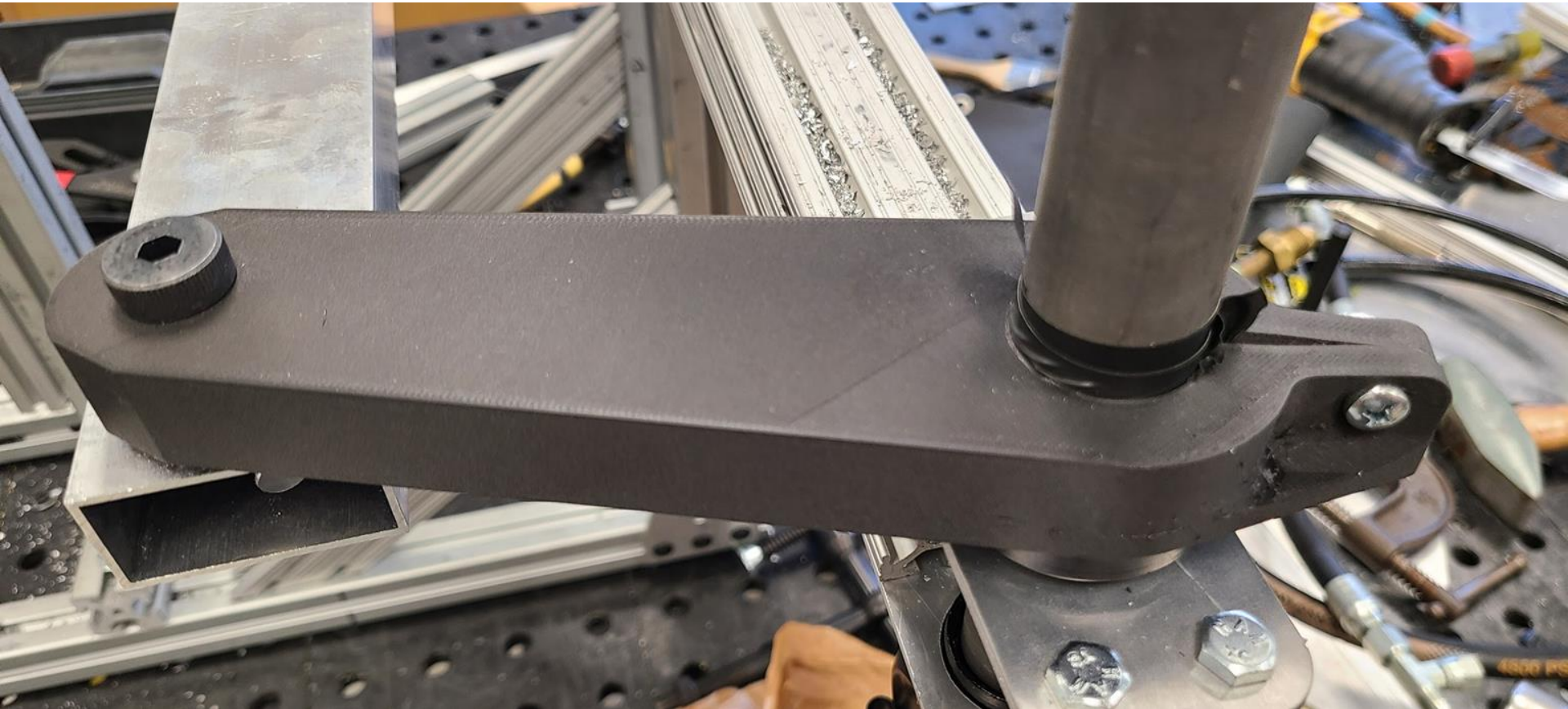
Steering



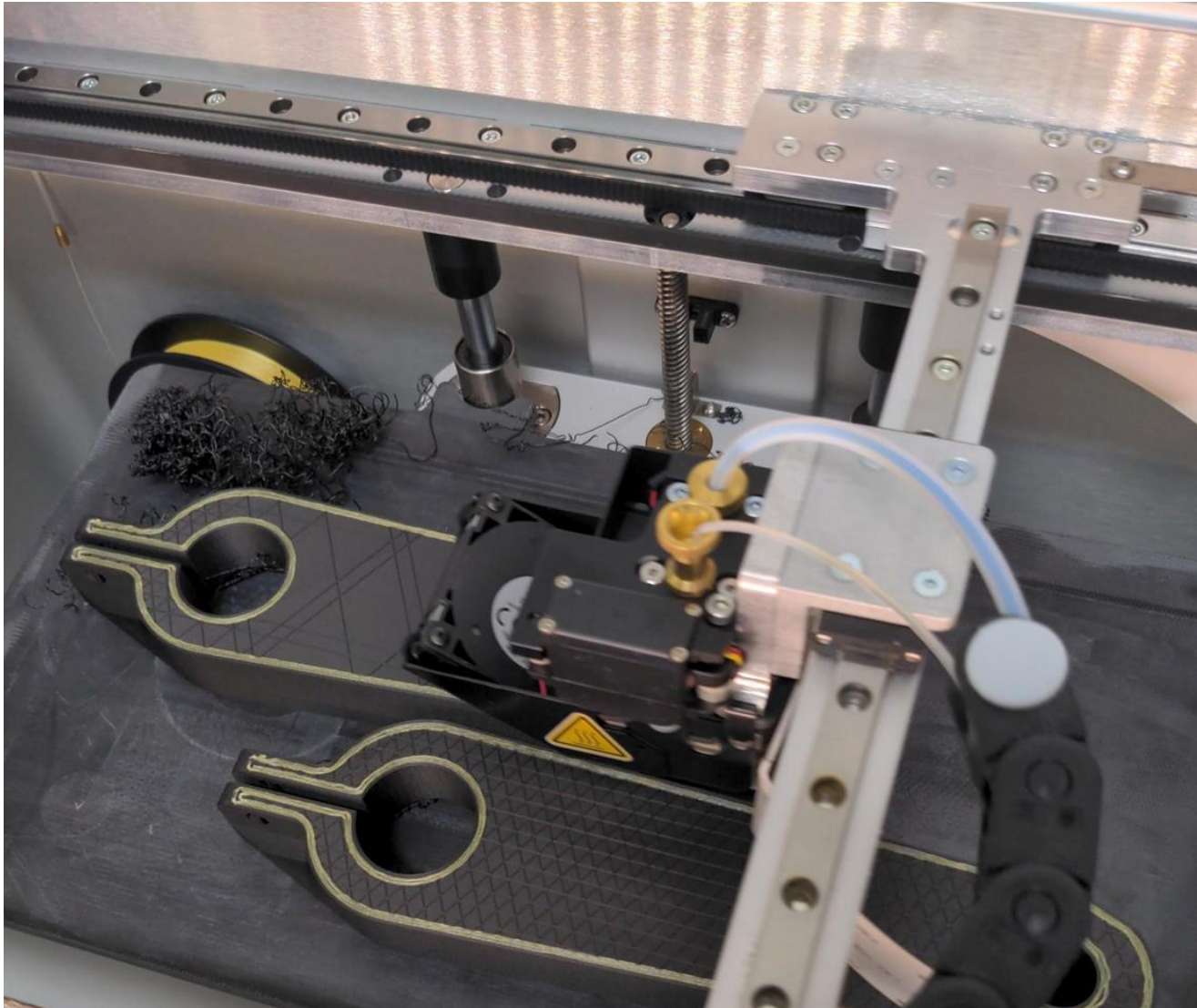
Steering



Steering Linkages



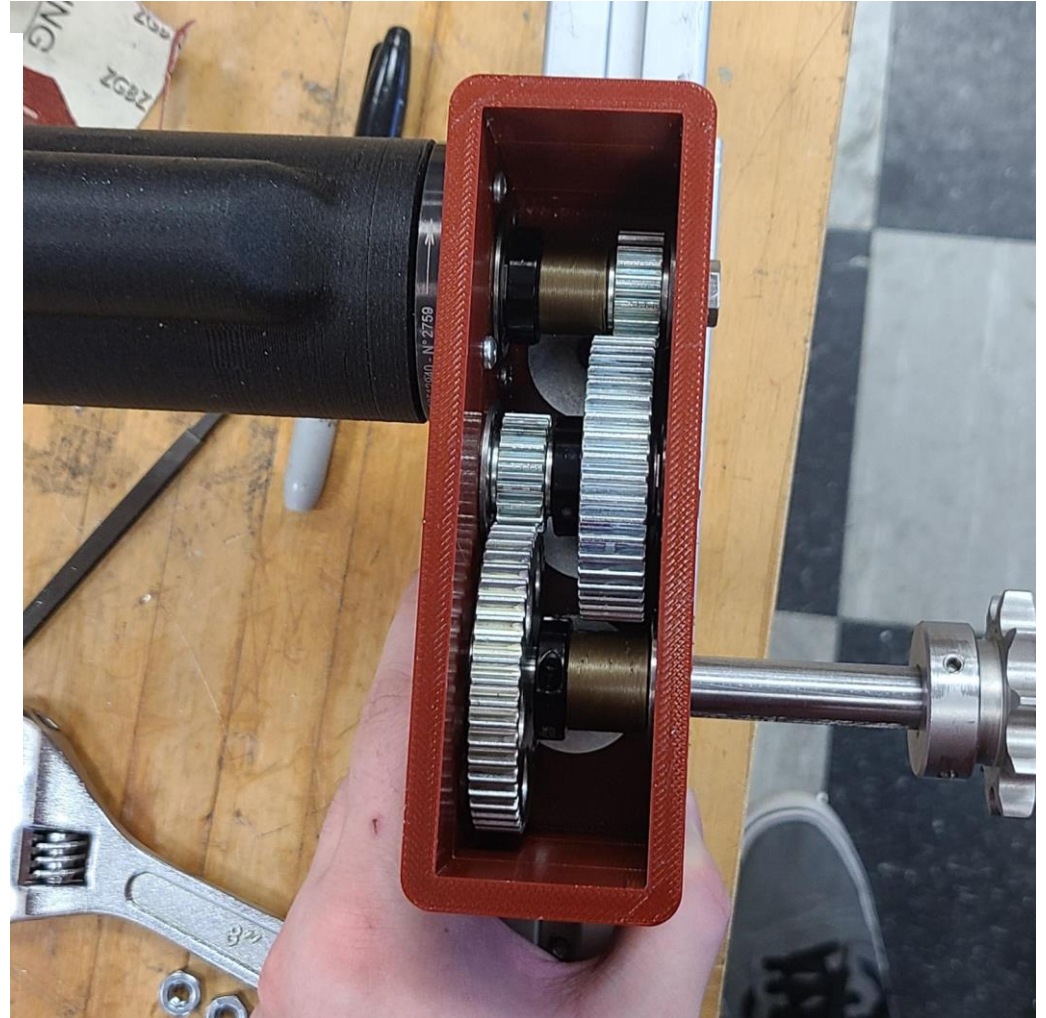
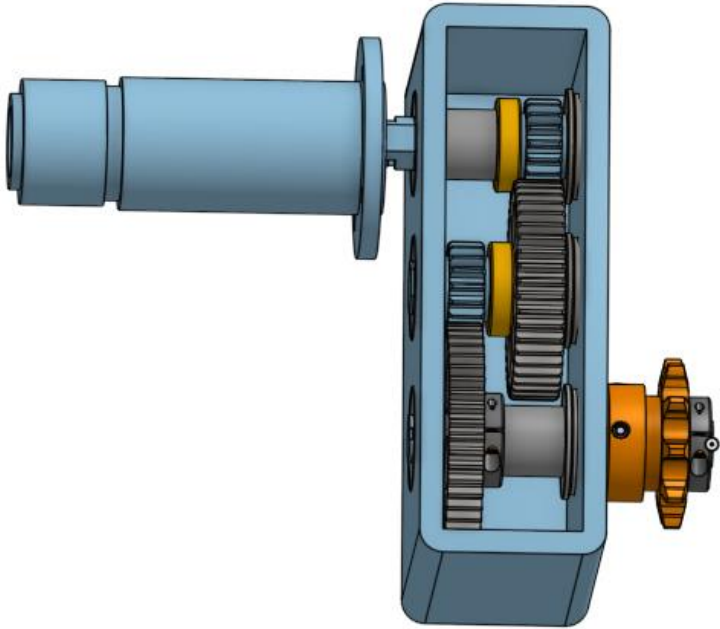
Steering Linkages



Gear Ratios

- We have 2 variable gear ratios and 1 static gear ratio
- Crank to pump gear ratio is 1:32
 - This is done so that we can get to higher RPMs with our micropump
 - This is also done to keep the gear ratio comparable to the regen circuit so that there is not a disparity in pressure

Input Gearbox



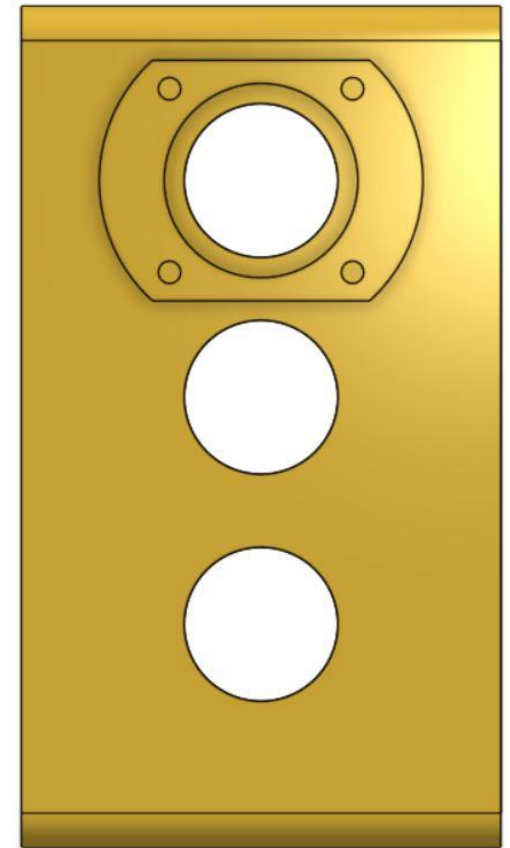
Input Gearbox



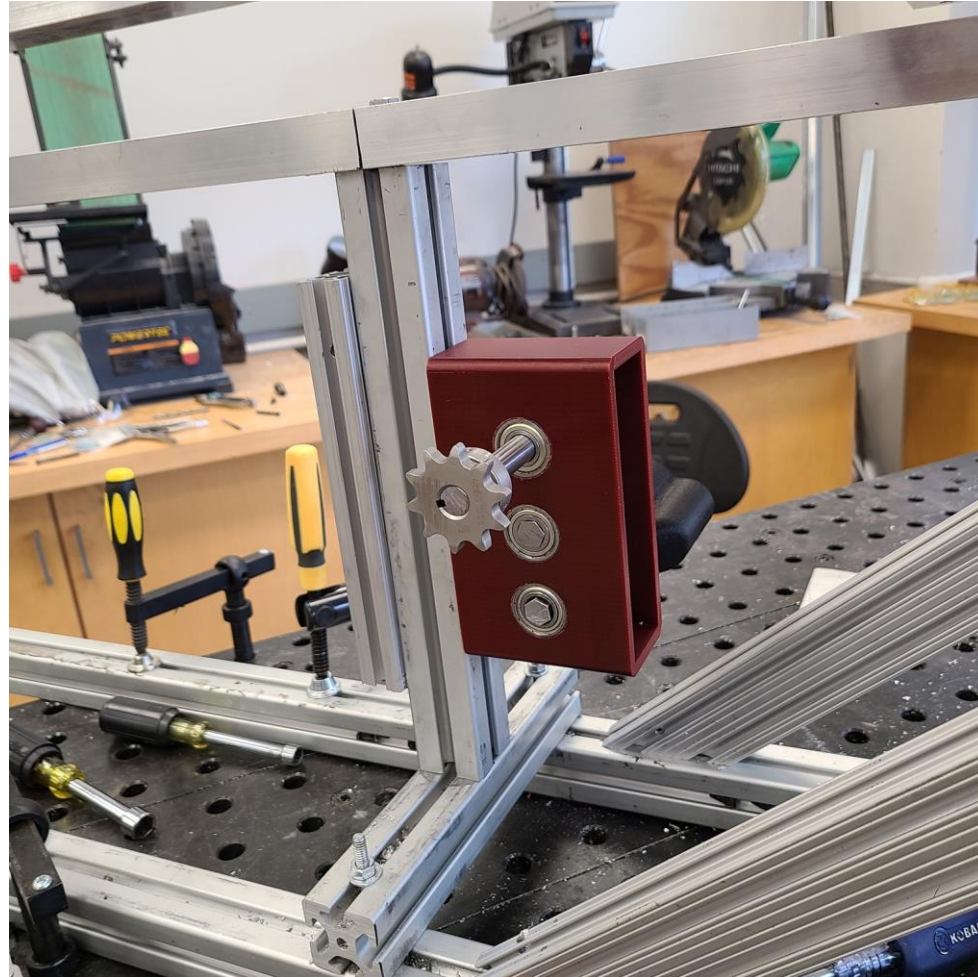
Printed
successfully
first time!

13-hour print
at 80% infill
(Afinia printer)

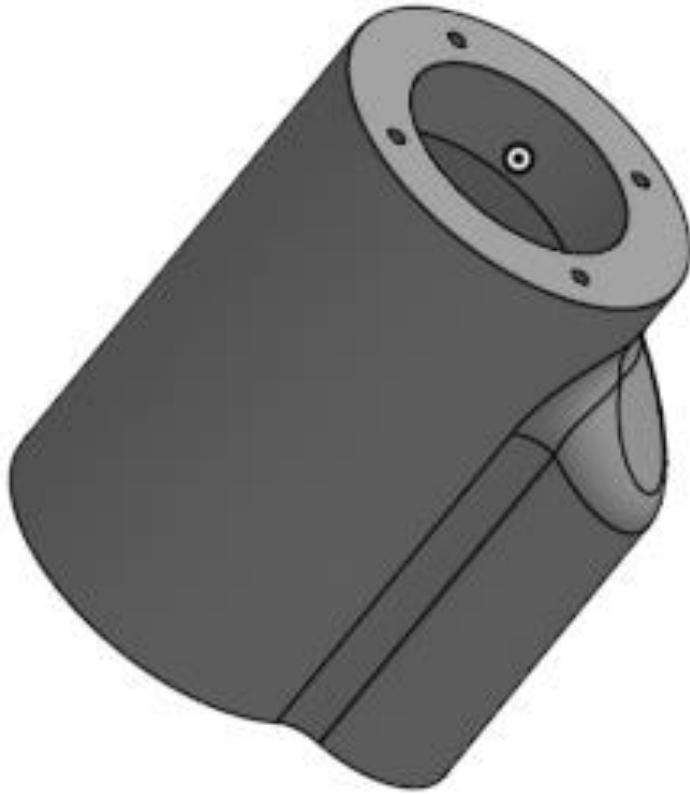
Protrusion for
mounting
pump housing



Mounting



Pump Housing



Pump Housing



Variable Gear Ratios

Human Power side

- We have decided to go with a cassette gear shift due to its versatility in terms of gearing options
- Minimum
 - 1:5 Gear Reduction
- Maximum
 - 1:1.1 Gear Reduction



Cassette Disk



2 Speed Gearbox



Regen Side

Minimum 1:4.78

Effective

Maximum 10:1

Desired Operation Speed

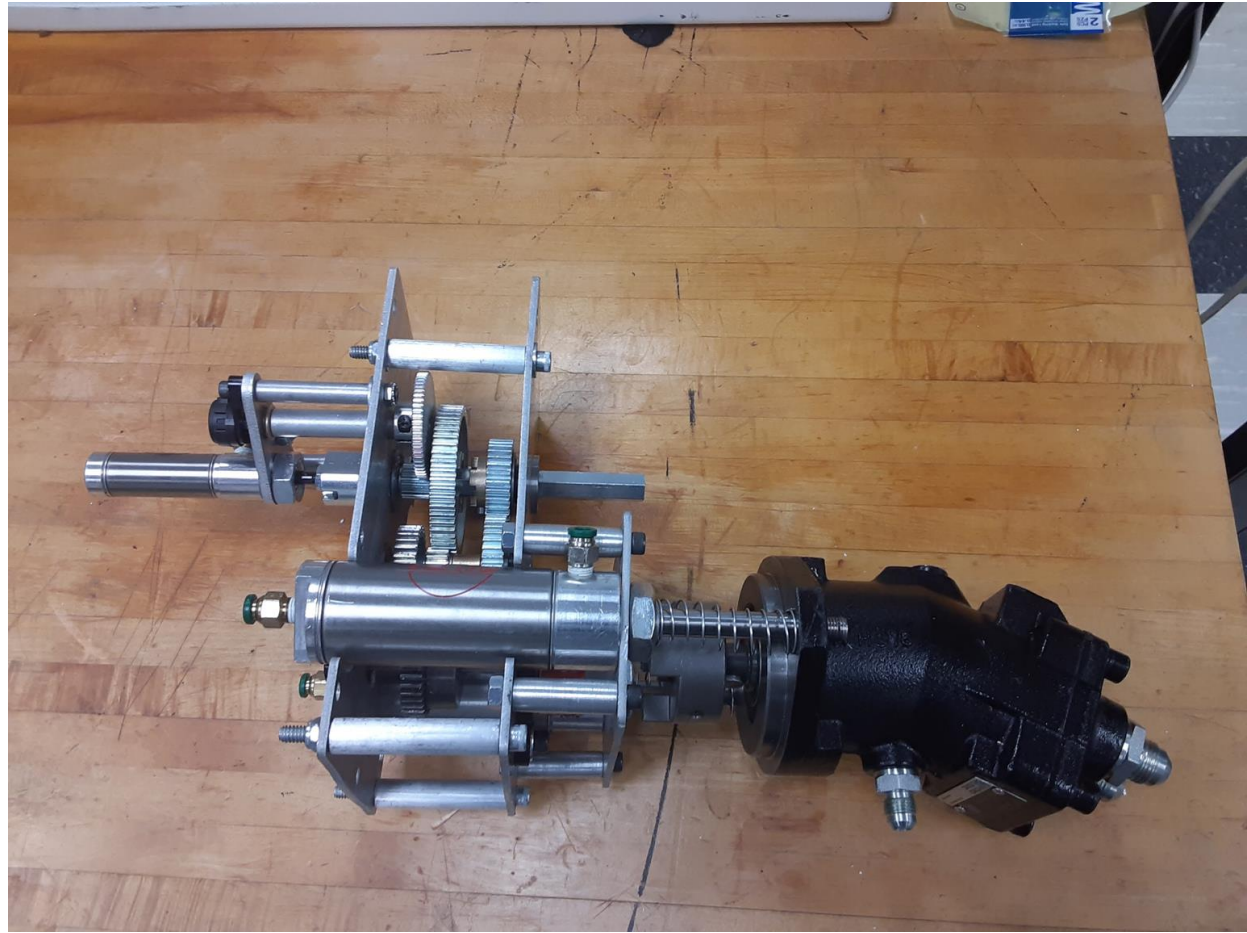
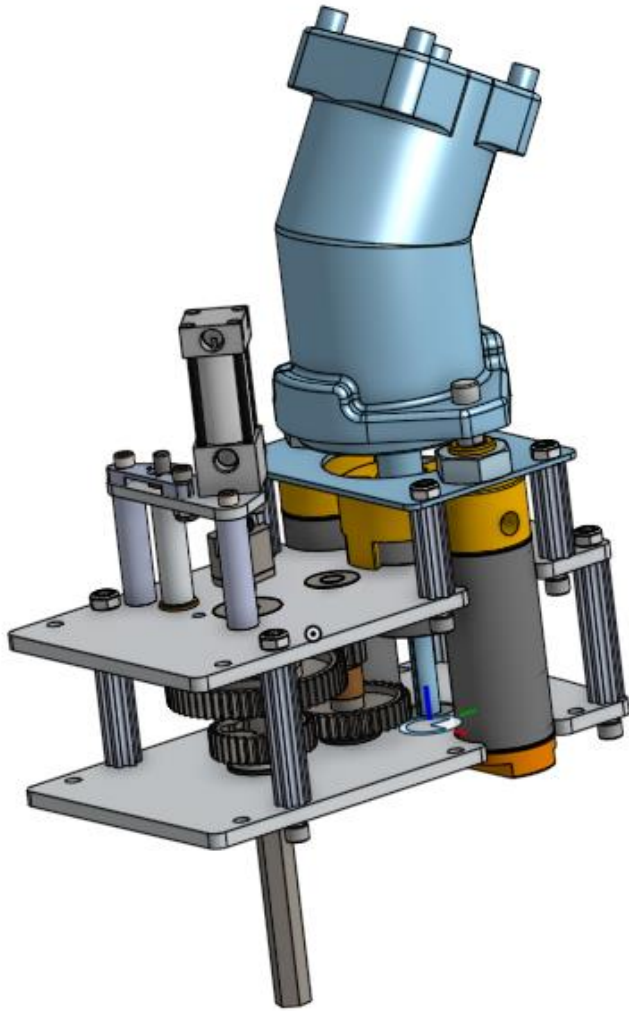


Pneumatics

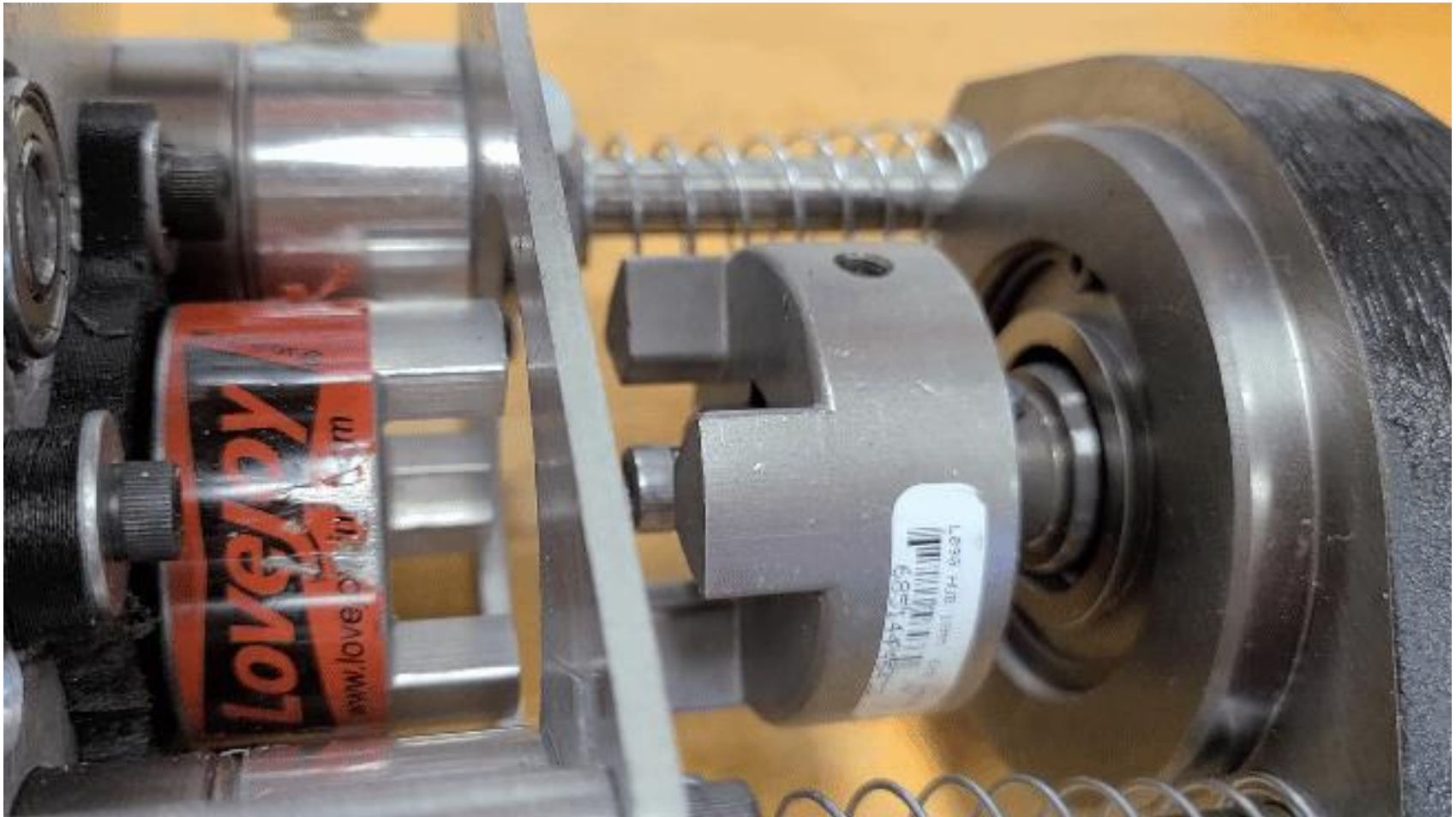
- A 2 speed gearing system that alternates between 2 gear ratios via pneumatic actuators
- The clutch is also be engaged/disengaged via pneumatic actuators



2 Speed Gearbox Design



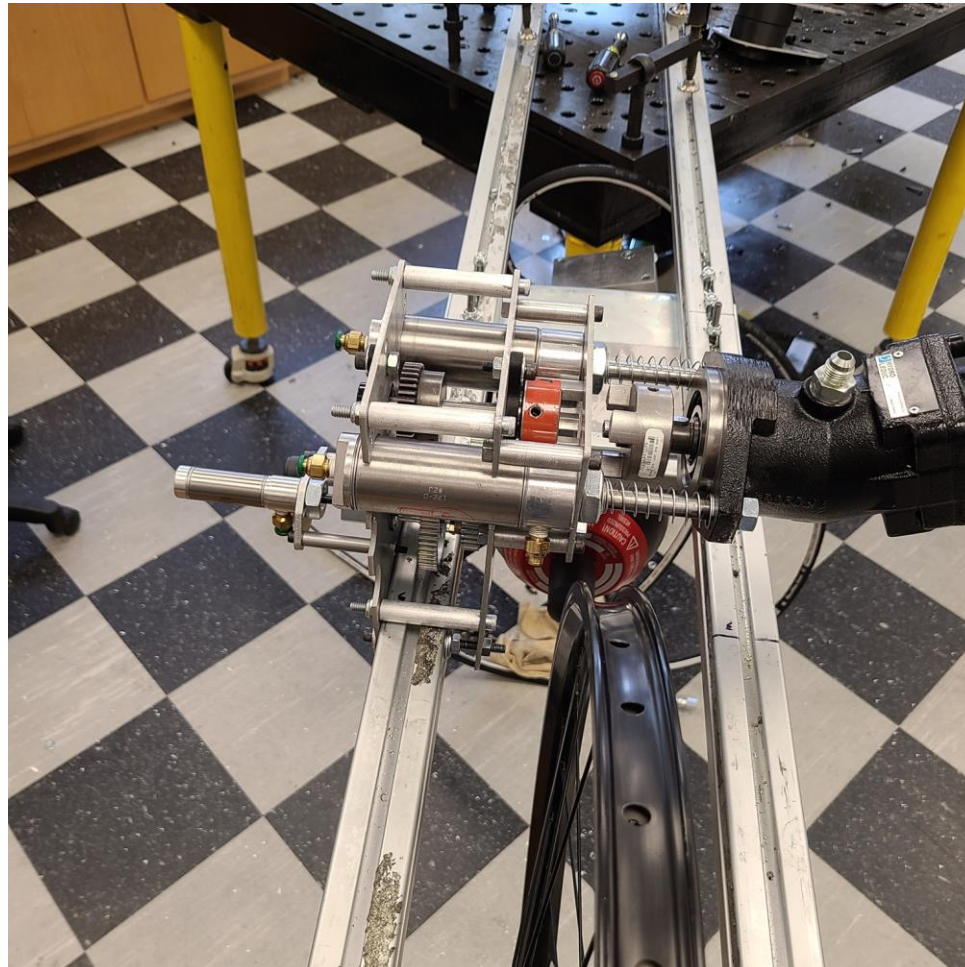
Pneumatic clutch



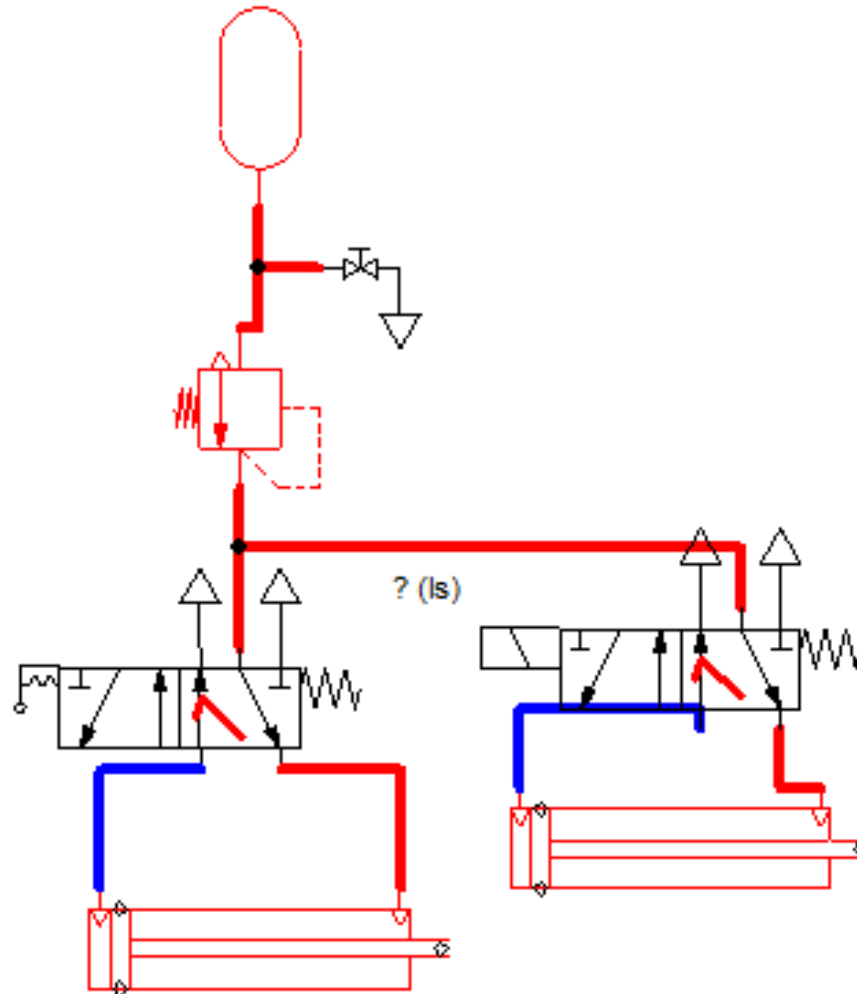
Pneumatic shifter



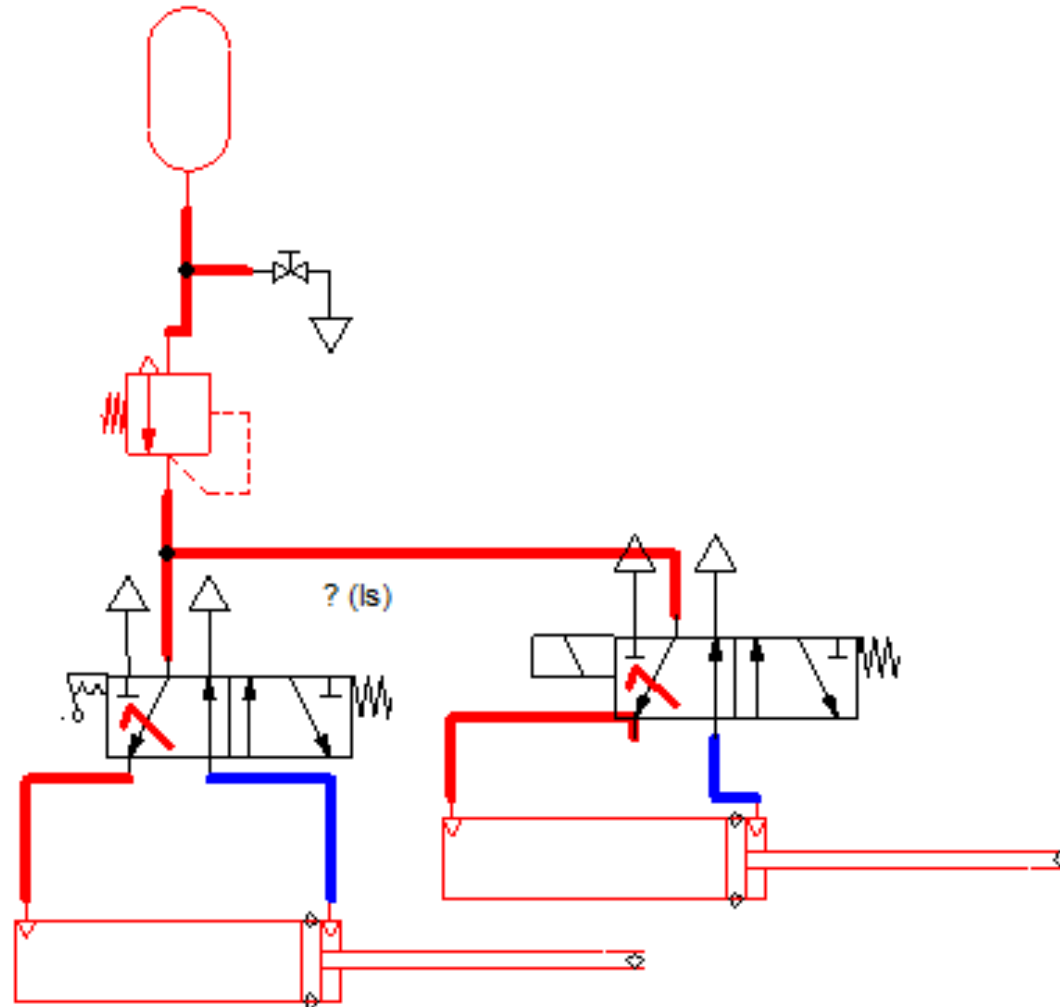
Gearbox Mounted



Pneumatic Schematic



Pneumatic Schematic



Projected Bike Specifications



Ideal Human Powered Speed: 13-15 mph

Projected Accumulator Speed : 29 mph

Bike Length: 6ft

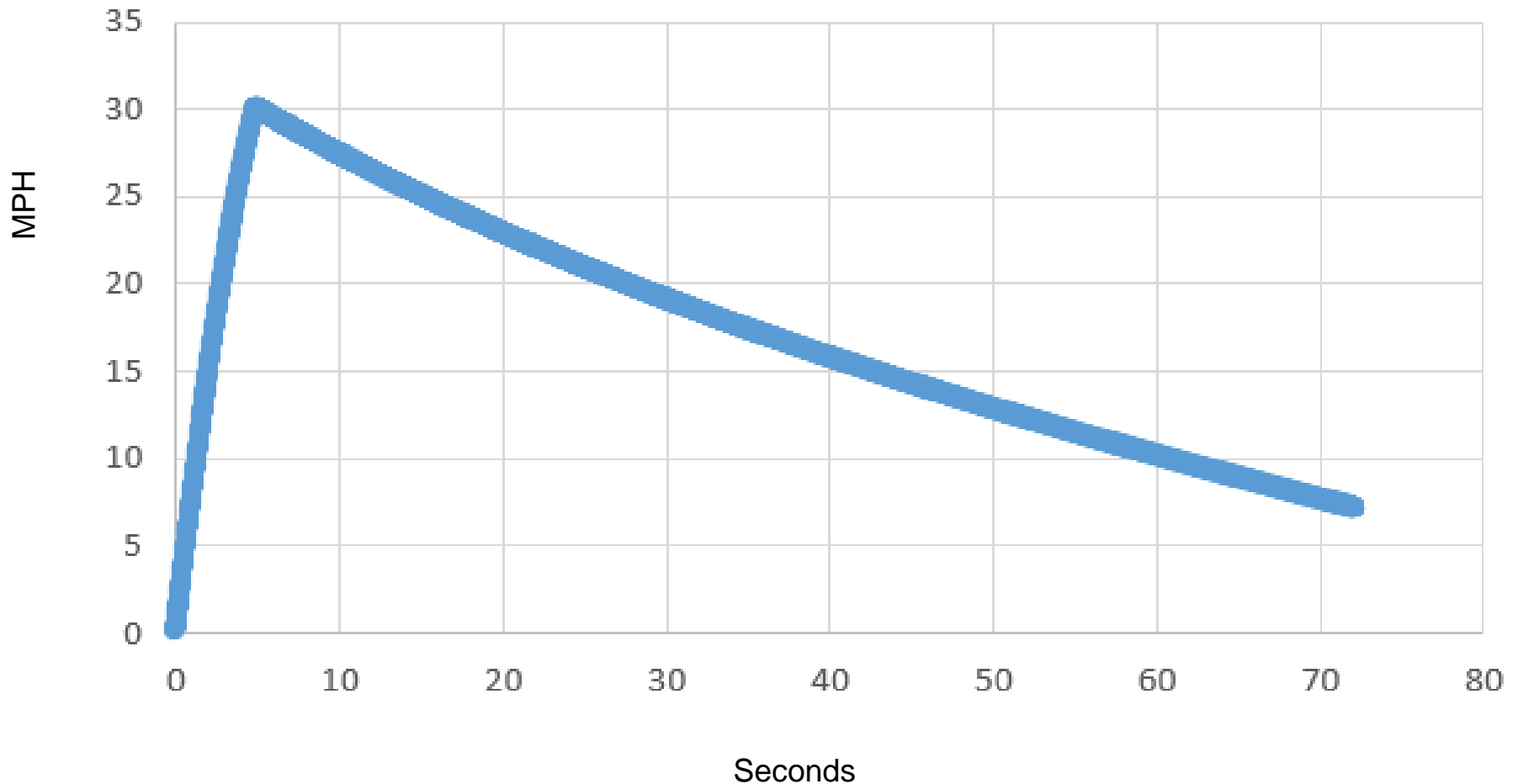
Width: 3ft

Weight : 140 lbs

Theoretical Expectations



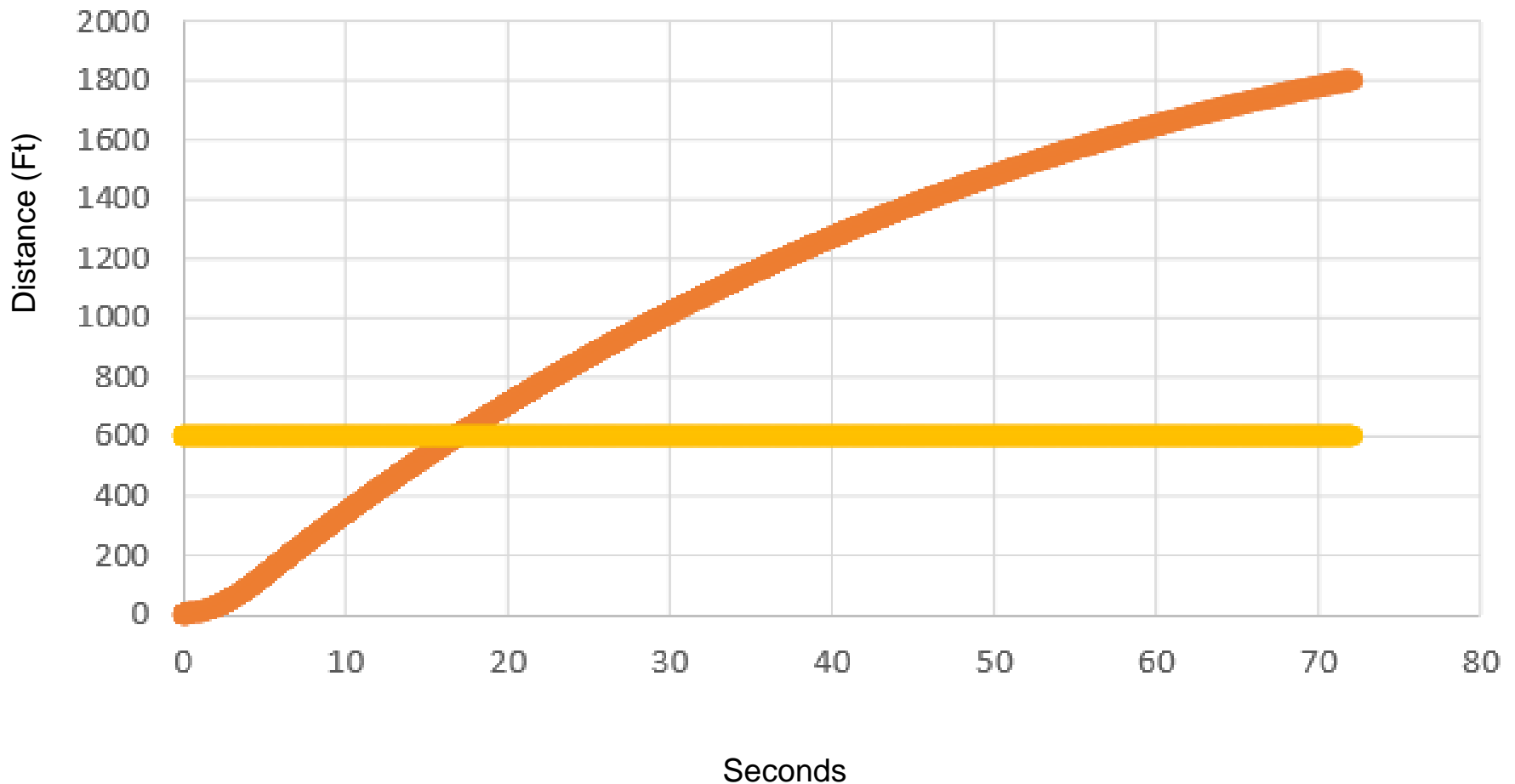
MPH vs Time



Theoretical Expectations



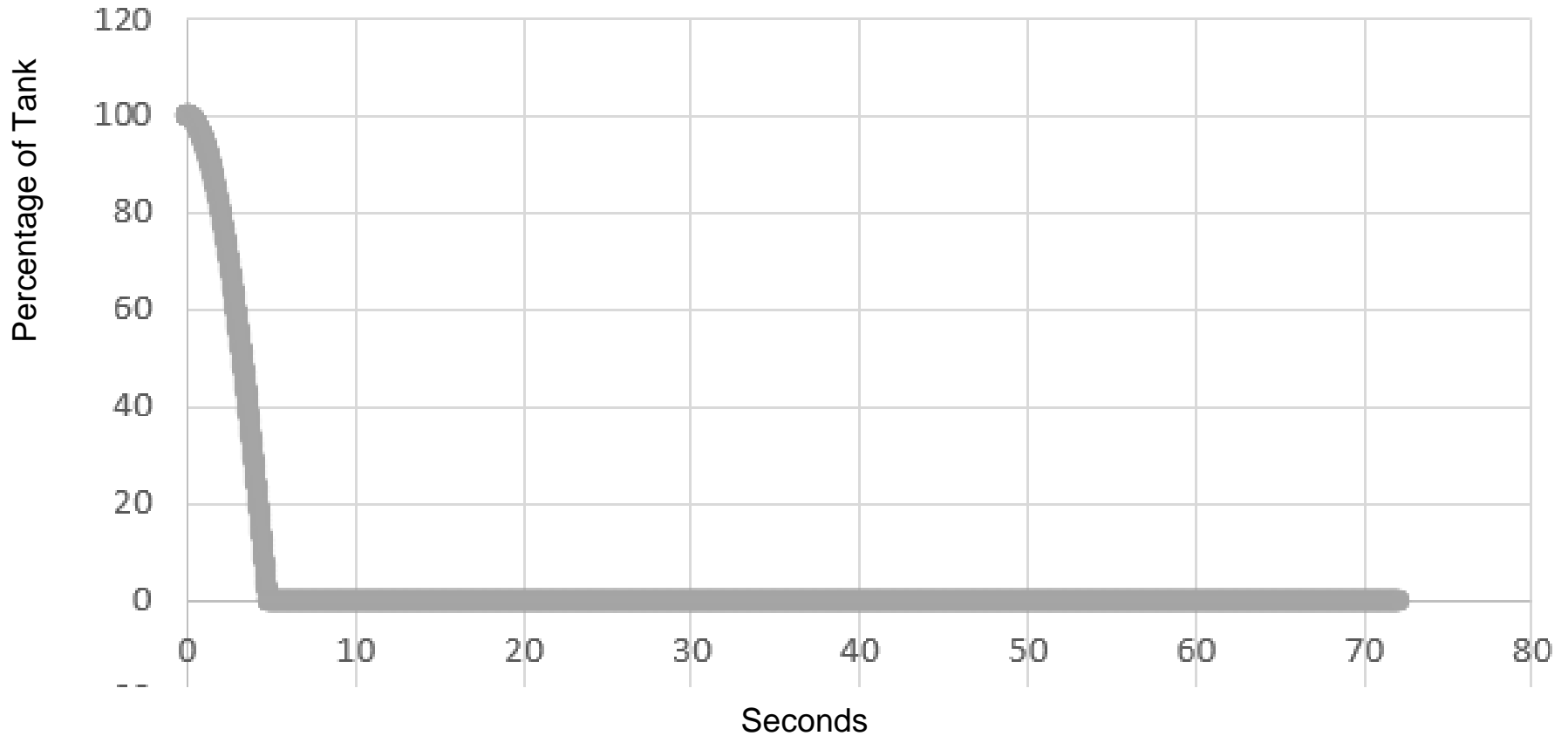
distance vs time



Theoretical Expectations



% of tank vs Time



PLC Operations

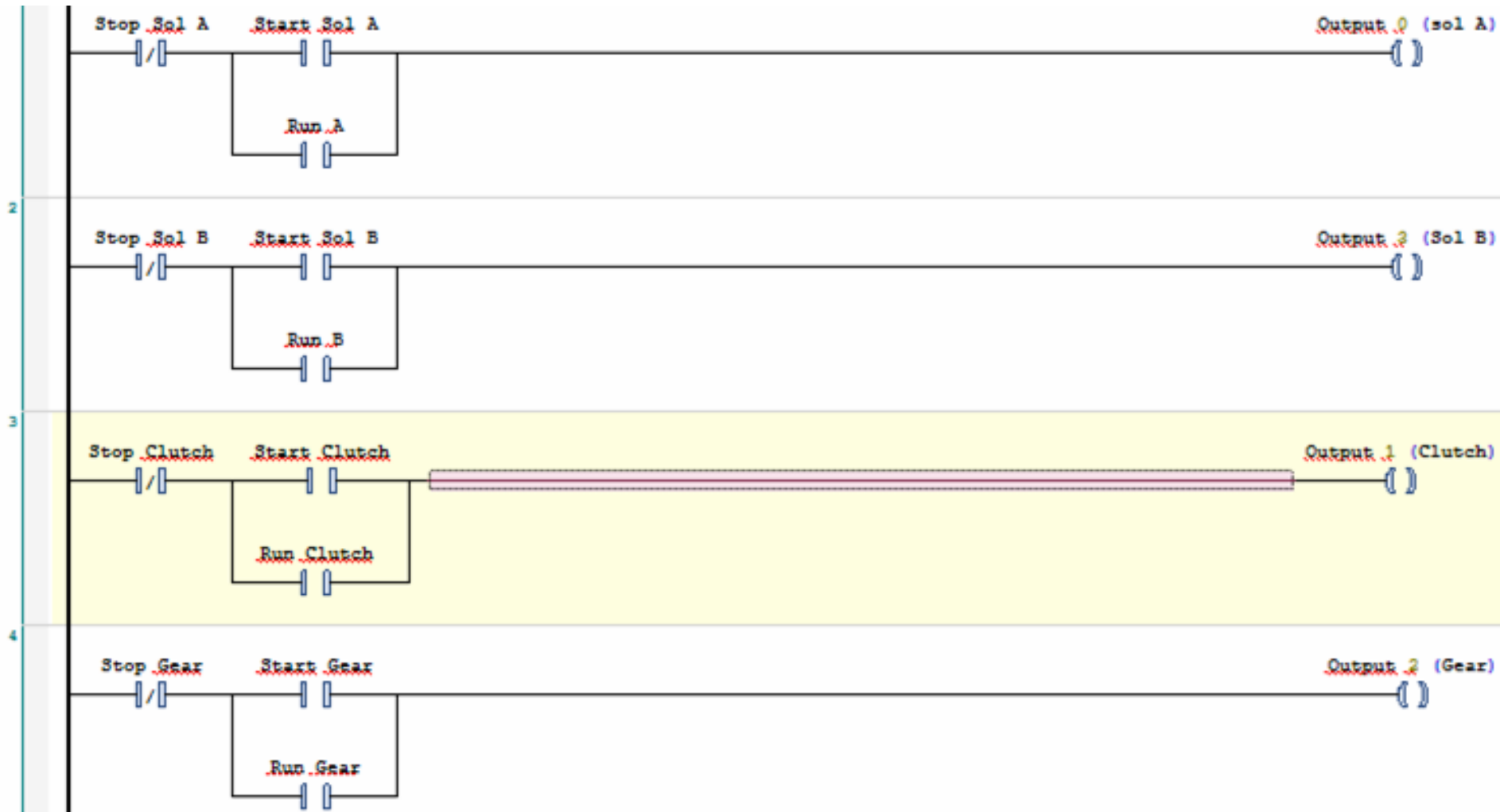
- Operate the pneumatic clutch
- Operate the 2 speed gearbox
- Operate the directional control valve



Program Setup

- Button 1: Activate sol A, clutch, gear shifter
- Button 2: Activate Sol B
- Button 3: Reset/ E stop

Ladder Logic Program for PLC

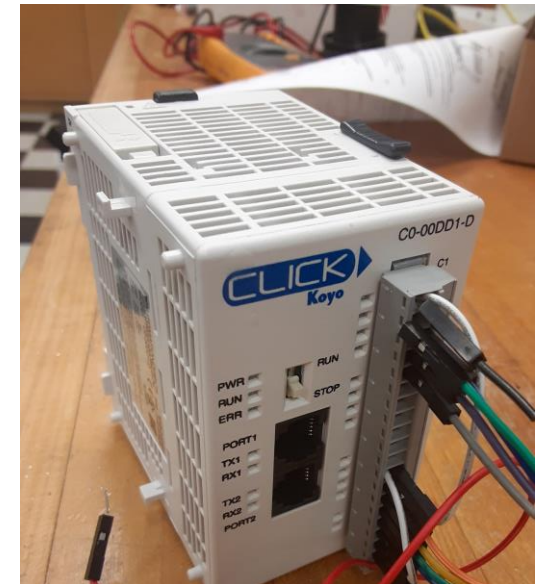


PLC Program Extended



PLC Choice

- PLC Click
 - Software was available
 - Had volumes of resources used to assist in programming and layout
- 24V Power supply
 - Use battery bank
 - Batteries in series to add V





Challenges

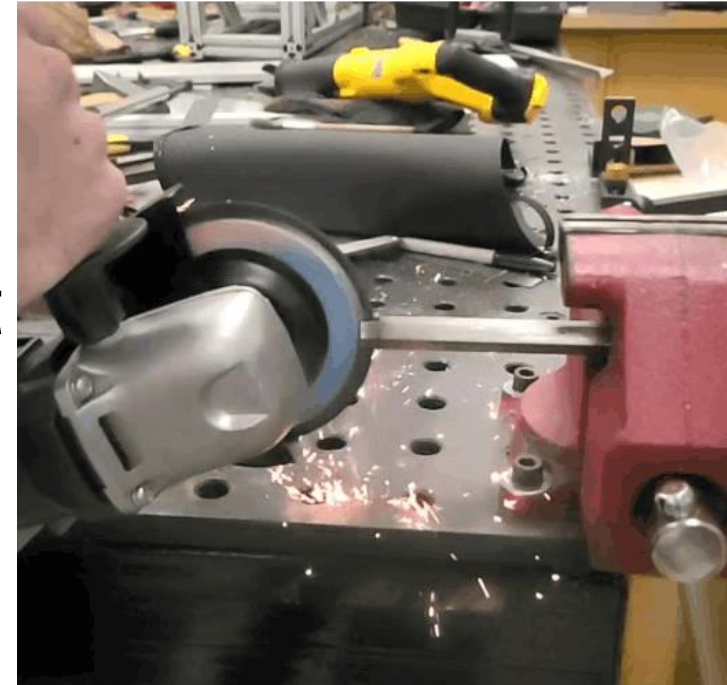
- Volunteers
 - Too few members
 - Not a lot of experienced members
 - Poor Communication
- Mechanical Components
 - Parts ordered too late
 - Focused too little on assembly
 - Not experienced with bicycle components
- Equipment Failure
- Pandemic/Covid-19 (shipping)

Learning as we go

- Efficient time management
 - Working when parts aren't physically available
- Maintaining healthy work schedule
- Supporting other team members
- Plan for different experience levels
- Teaching members while maintaining work efficiency

Practical Skills Learned

- Safe operation of equipment (i.e. drills, reciprocating saw (Sawzall), water jet cutter (WAZER), 3D-Printers, grinder)
- Equipment maintenance
- CAD Design (Onshape)
- Bicycle components
- Effective uses of different tools



Social/Teamwork Skills Learned



- Prioritization and delegation of tasks
- Learning to effectively teach each other
- Seeking collaboration
- Concise and effective communication

Machines/Software Used



- WAZER Water Jet Cutter
- Automation Studio
- Onshape
- Afinia 3D Printer
- Markforged 3D Printer
- Basic metal working
- General hand tools
- Excel

Water Jet Cutter (WAZER)



- Setup
 - Proper set up procedures
 - Proper setup of the .dxf files
 - Correctly securing material to cut bed
- Running
 - Looking for cut errors / General supervision
- Maintenance
 - Diagnosing issues
 - Fixing issues
 - Preventing further issues

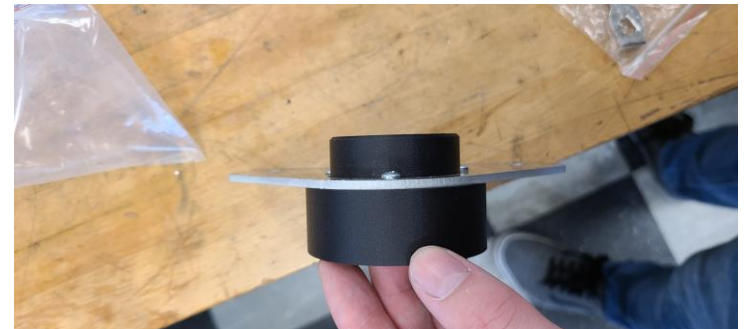
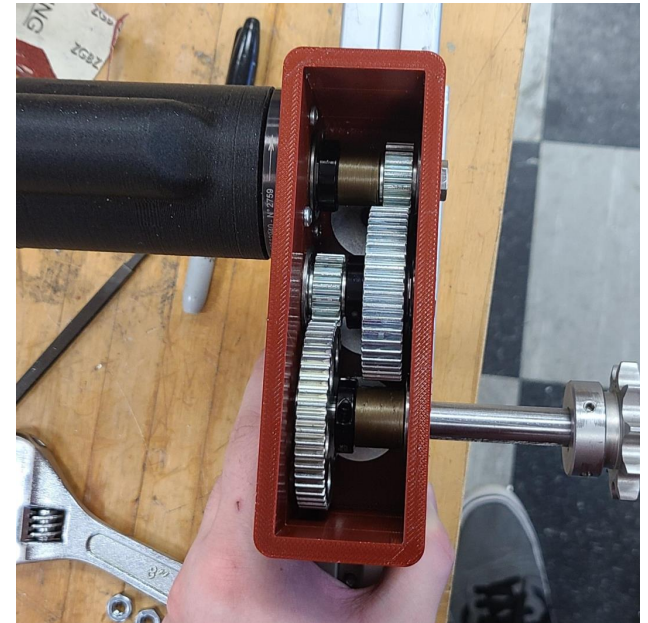
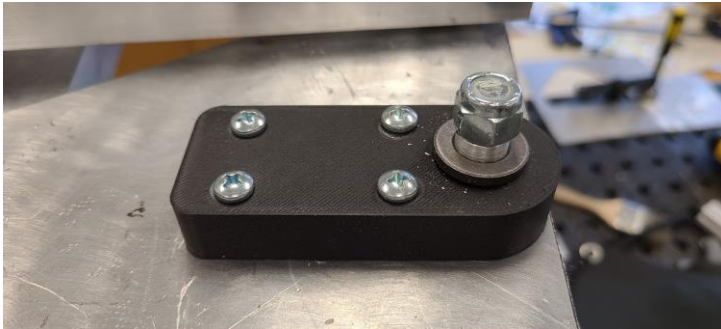
Additive Manufacturing (3D-Printing/Modeling)



- Using Onshape
- Modeling bike parts to fit a custom bike
- Assembling parts to simulate functions
- Operating 3D printers to create 3D modeled parts with PLA, Kevlar, Carbon Fiber, Polycarbonate, and Nylon
- Altering 3D printed parts to operate with bike



Parts we designed and manufactured



Communication / Team Management



- Weekly Meetings
 - Task delegation
 - Group problem solving
 - Checkups
- Individual Meetings
 - Work 1:1 with team advisor
 - Prevented further collaboration
- Communication
 - Email
 - Text

What could be done differently



- Create CAD of the entire bike first
- Deadline for delegated tasks
- Avoid over reliance on machines (WAZAR)
- Minimize custom fabrication (almost impossible)
- Better Organization and structure
- More recruitment

What we will continue working on



- Electronics
 - Flesh out and wire PLC
- Mounting
 - Mount Motors
 - Fully mount manifold/hydraulics
 - Set up power input
- Steering
 - Add Handlebar
 - Attach wheels to steering hook
 - Finish manufacturing plates
- **Make it race worthy!**



Thank you for your time!