

Final Design Review

Featherweight Cycles - 2022



Introductions



As a team of five mechanical engineering students at Cal Poly San Luis Obispo, we have all been very excited to partake in the Fluid Power Vehicle Challenge!







Main Design Objectives

Vehicle Frame

- Decrease Frame Weight compared to last year's design
- Improve Sprint Performance

Hydraulics

- Improve
 Efficiency
- Fix direct drive mode
- Implement Hydraulic Hardlines

Pneumatics

- Implement a position controlled pneumatic seat
- Test and Iterate

Mechatronics

- Optimize Current Charge Platform
- Implement Seat Position Control Model

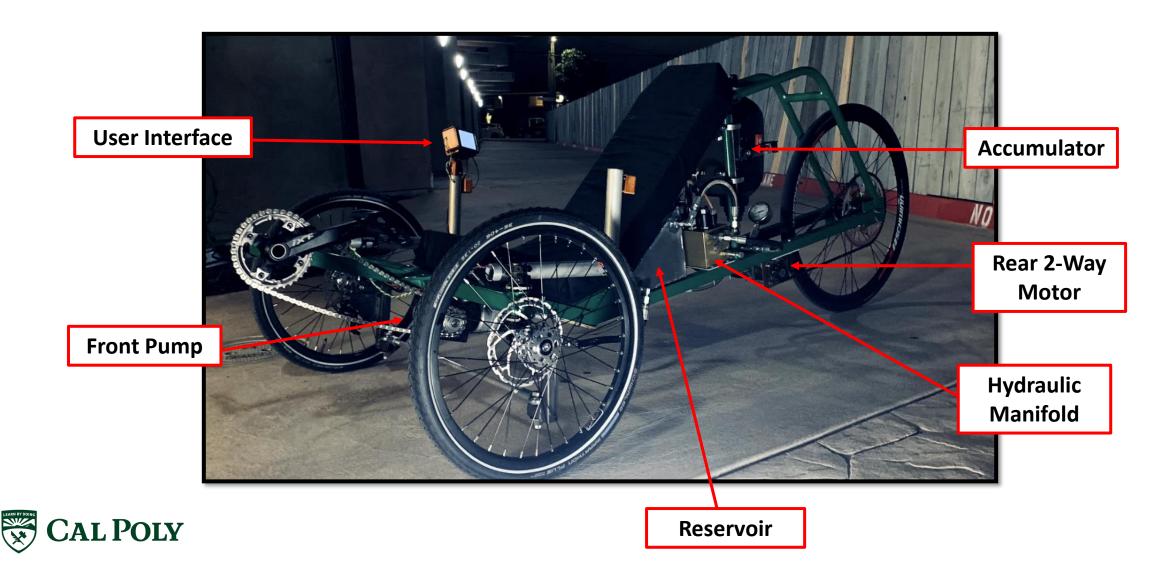


Summary of Midway Presentation



Previous Vehicle (Cal Poly 2021)





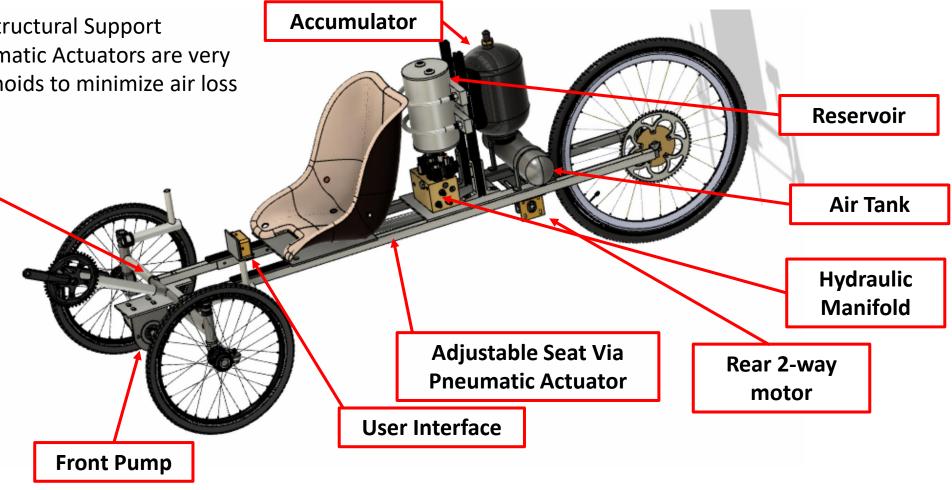
Midway Review Summary



Judge Feedback:

- Add Frame Structural Support •
- Ensure Pneumatic Actuators are very ٠ close to solenoids to minimize air loss

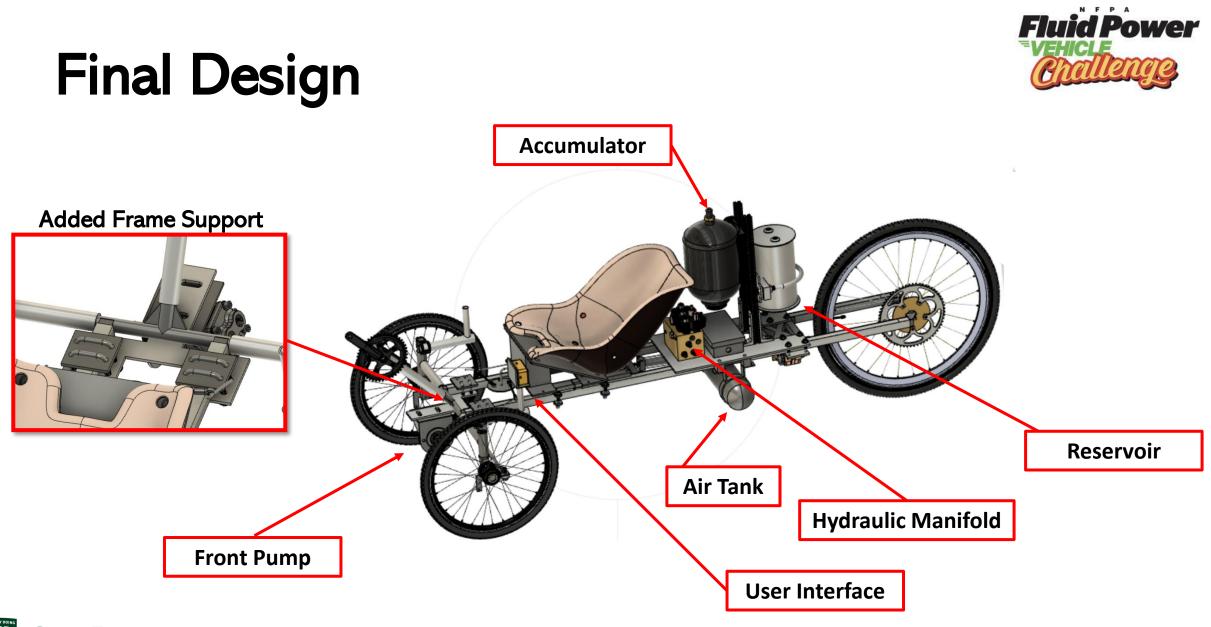








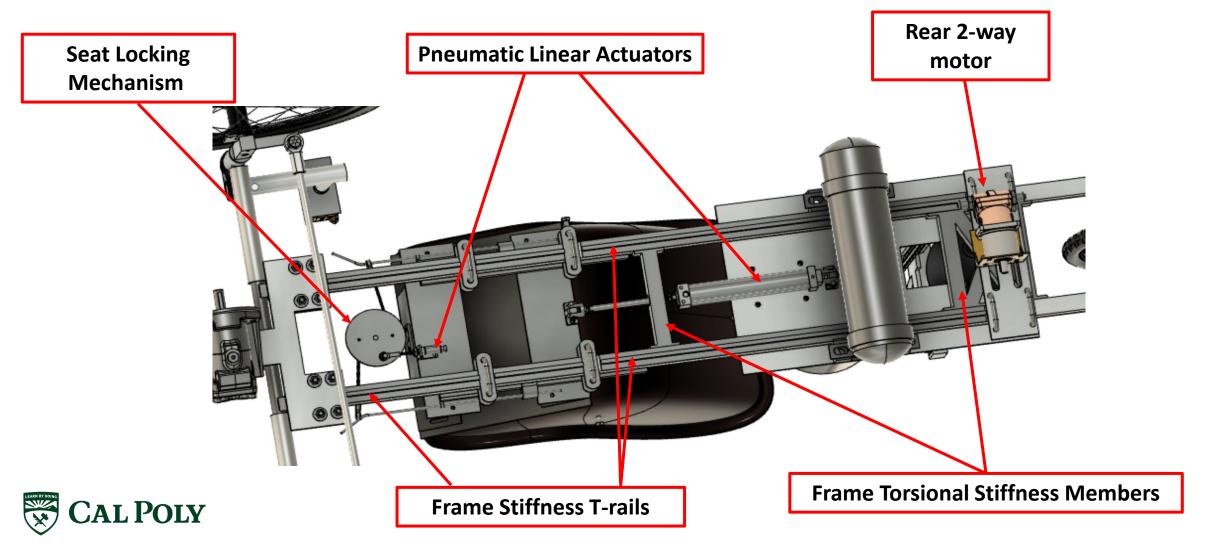








Final Design (Bottom View)

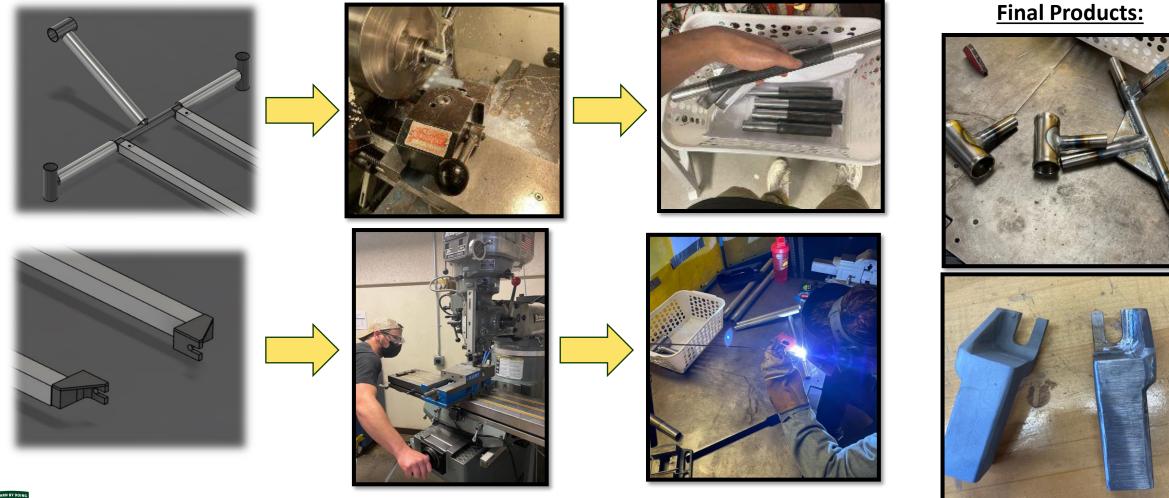


Frame Sub-Assembly





Manufacturing Frame Steel Inserts

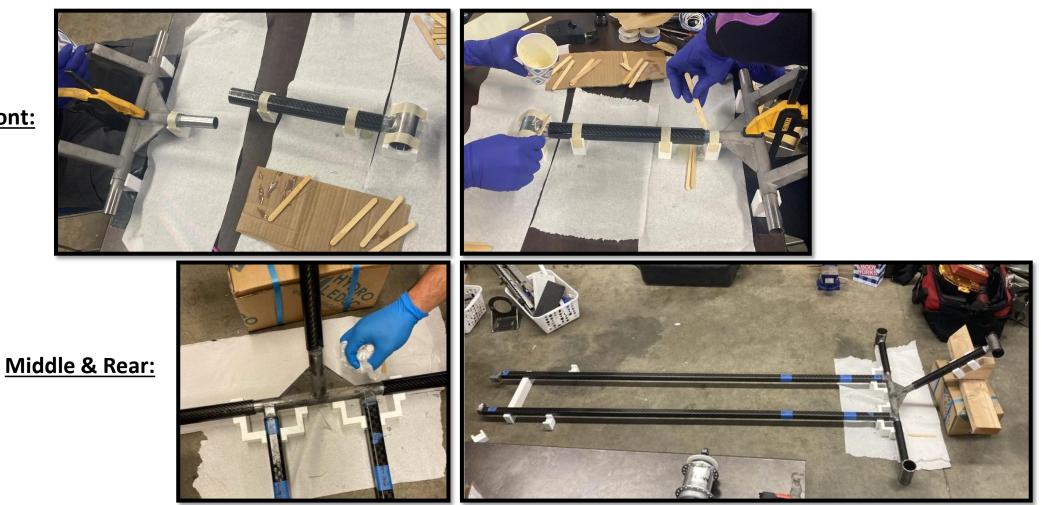






Frame Bonding

Front:



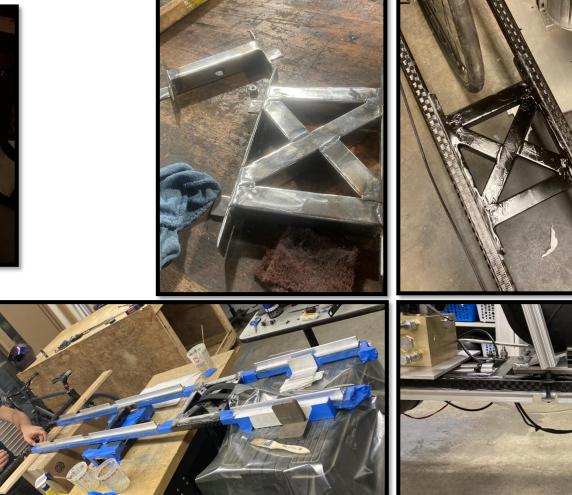


Frame Stiffness Problem/Solution





Solutions:





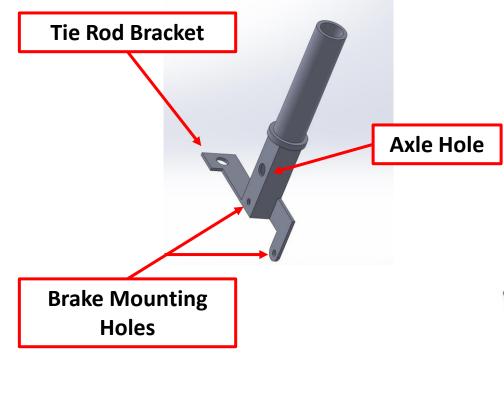


Steering Sub-Assembly



Manufacturing Headtube Assembly

Design:



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Headtube Assembly:





Brake Assembly:









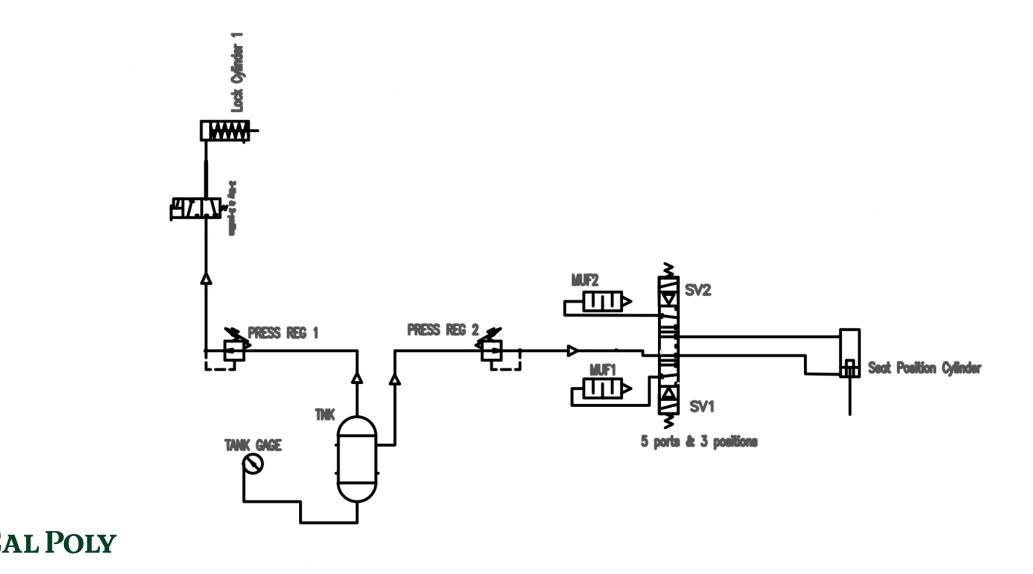


Pneumatic Sub-Assembly



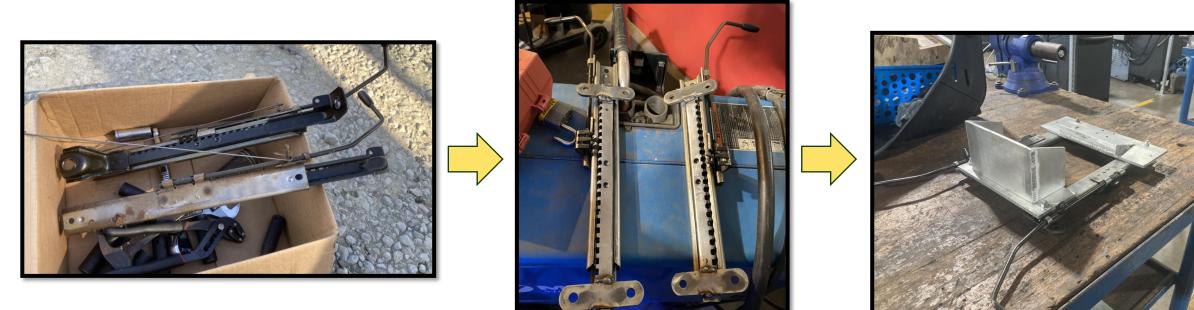
Pneumatic Circuit Diagram







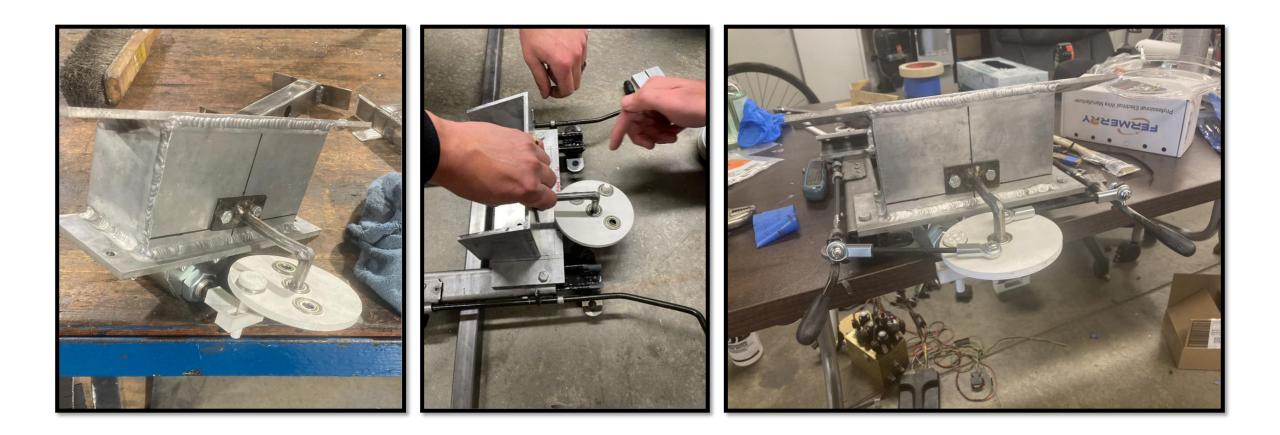
Seat Rail Assembly







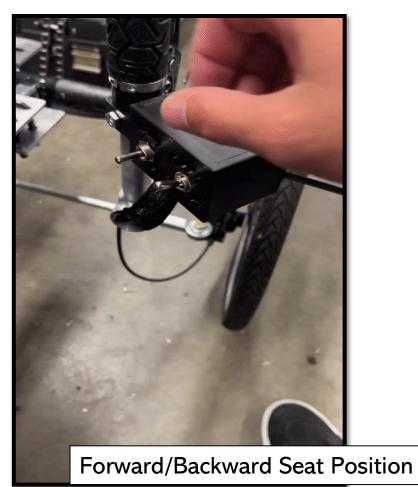
Locking Mechanism Assembly

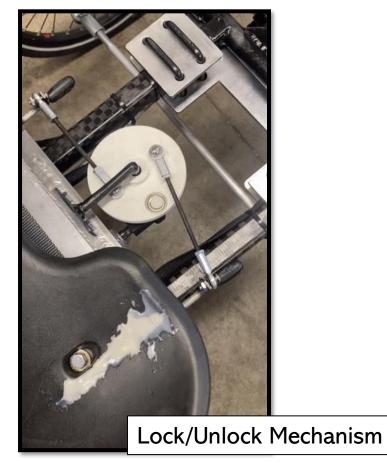






Testing Actuation





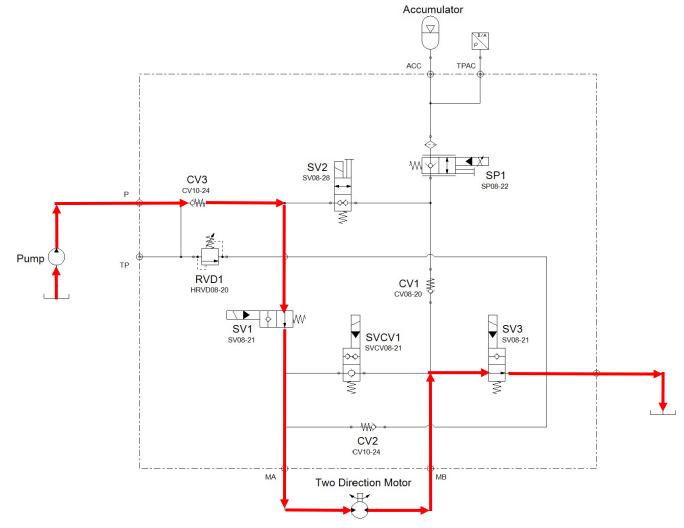


Hydraulic Sub-assembly

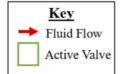




Direct Drive Mode

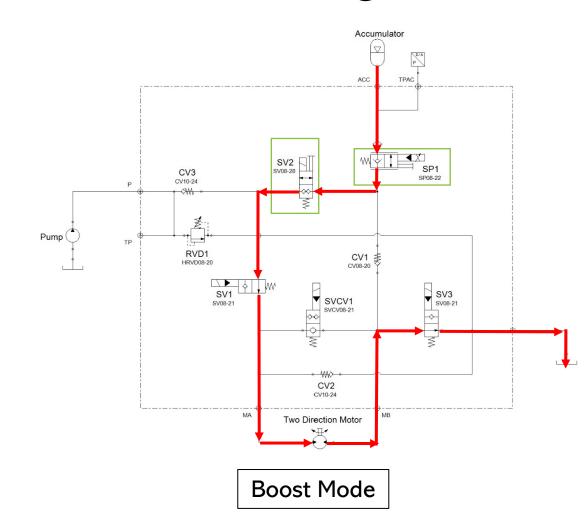


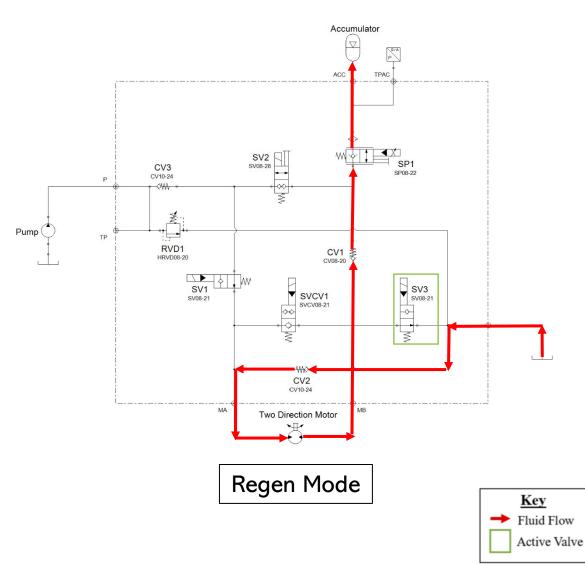




Boost & Regen Mode



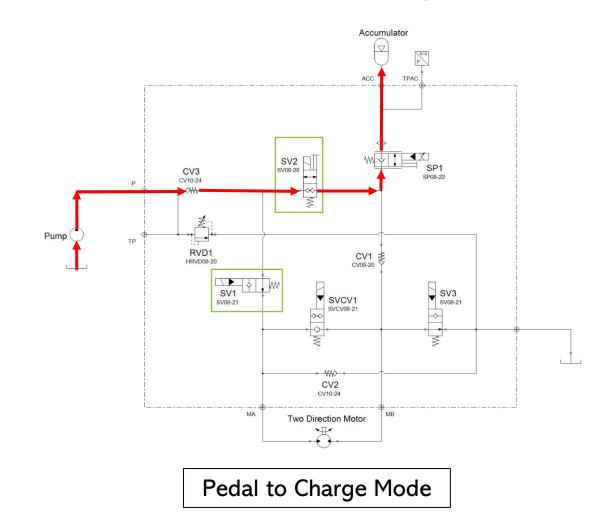




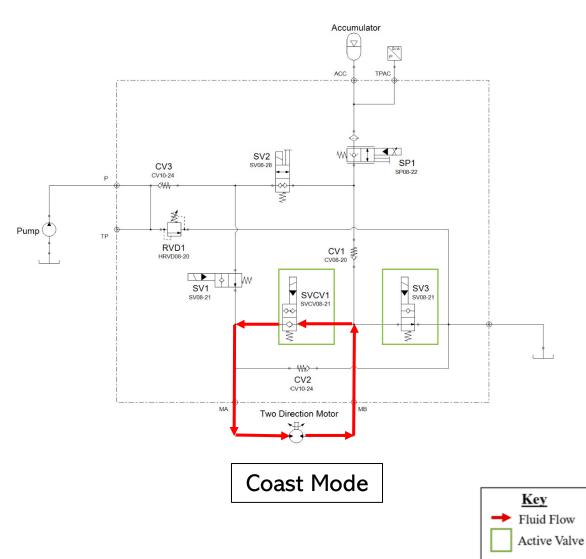


Pedal to Charge & Coast Mode





AL POLY



Reservoir Manufacturing





- Larger capacity of 1.8 gallons
- 6061-T6 Aluminum, 6" nominal pipe with water jet top & bottom for TIG Welded Assembly
- Made to minimize leak points on Reservoir





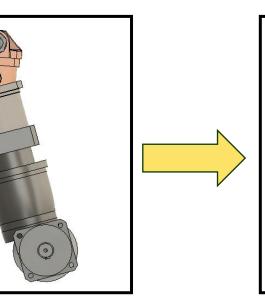
Front Pump Conversion



<u>Old Pump</u>

Bosch 5CC Bent Axis Pump:

- Weight: 5 lbs
- 5 cc/rev displacement
- Apex Dynamic Hypoid Gearbox 4:1 Ratio (10:1 overall from crank to pump)



New Motor



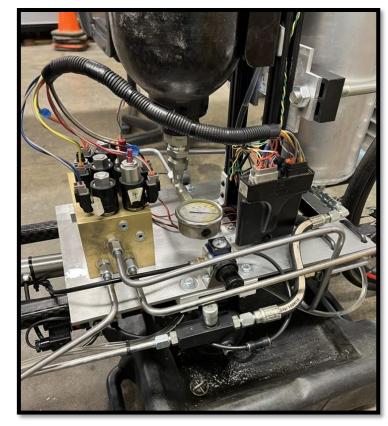


Hydraulic lines Manufacturing



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Hardlines





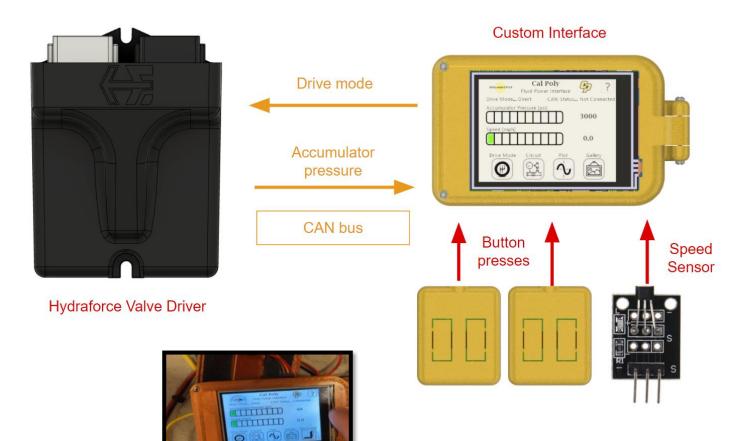
Mechatronics Sub-Assembly



Mechatronics Implementation



- Touch screen display to adjust drive mode
- CAN protocol used to communicate with hydraulic controller
- Hall-effect and pressure sensors for real time speed and pressure readings

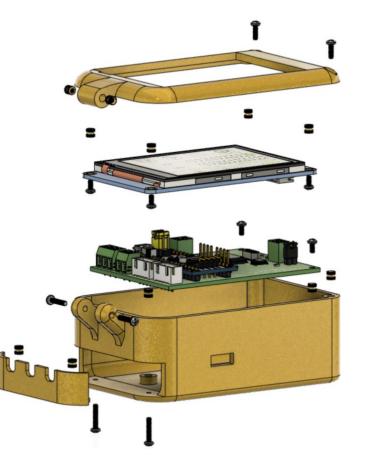




System Design

- Position Controlled Pneumatic Actuation
- Handlebar Mounted Hard Switches
- Electronic Relays for 12V power to solenoids connected to Nucleo development board.







Final Vehicle & Test Results





Fully Assembled Vehicle







Testing Results

Test	Distance	Result
Sprint I	500 ft	29 sec
Sprint II	500 ft	31 sec
Endurance I	1.45 miles	20 min
Endurance II	1.50 miles	20 min
Accumulator Charge Time	-	5 min









Final Reflection

Biggest Challenges

- Design Iteration
- Manufacturing Time

Recommendations for Next Year's Team

- Optimize rear section of composite frame design
- Add Accumulator Dump by replacing CV1
- Focus on improving Pneumatic and Hydraulic systems
- Include touch controls for pneumatic seat with UART communication.

Lessons Learned

- Everything Takes Longer Than Expected
- Divide and conquer, but maintain good design communication
- TEST, TEST, TEST



Questions?



