

N F P A

Fluid Power

VEHICLE

Challenge



NFPA
Education and
Technology
Foundation

Final Presentation
Milwaukee School of Engineering
Advisor: Dr. Luis A. Rodriguez



The Team



*Left to right: Kyle McComb; Brandon Stevens; Michael Tulsy; Alan Xiong;
Jeffrey Kaas, CFPHS; Steven Hegeman; Bryce Krueger*

Problem Statement

Develop a human powered vehicle to:

- Transmit power through hydraulics
- Compete in Sprint, Efficiency, Regeneration, Endurance
- Engage in fluid power and garner interest

2022-2023 Design



Tricycle Downsides

- Low stability at high speed

Chain/Gear Issues

- Proper tensioners are vital

Hydraulic Design

- Small motor = not enough flow and torque; low speed



Design Objectives

- Produce an original design
- Tailor our design for speed and simplicity
- Create a reliable and safe vehicle
- Unique pneumatic application



Preliminary Designs

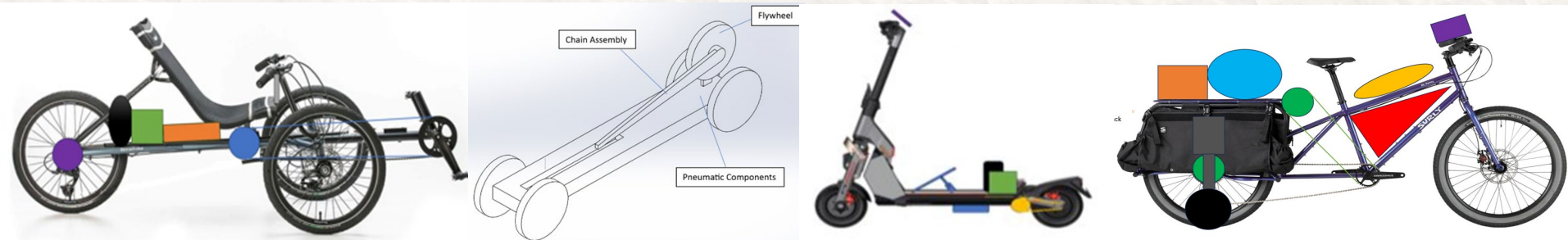


Recumbent Trike

Rower

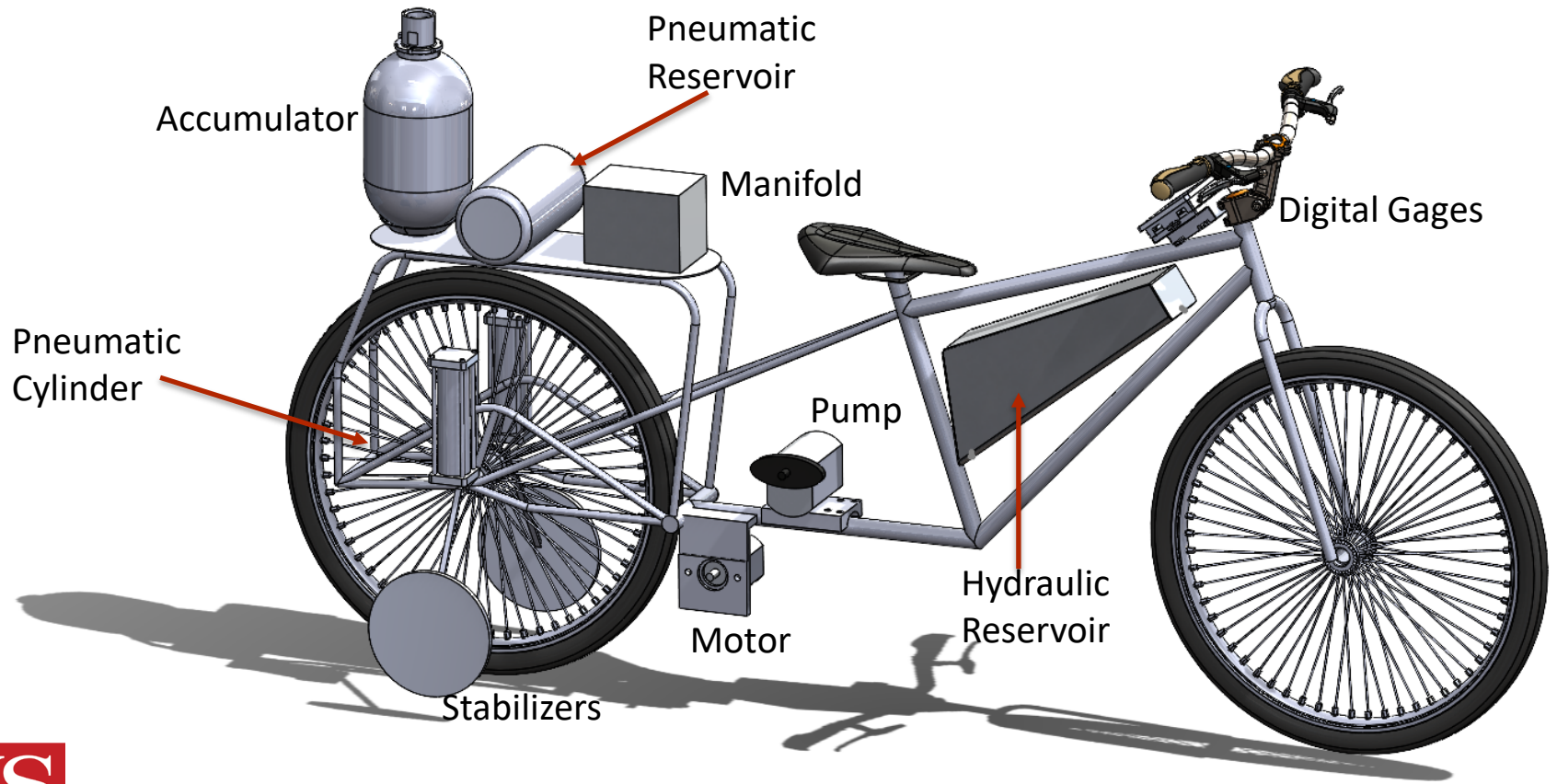
Stepper Scooter

Stabilized Bicycle



Criteria	Weight	Design #1 Recumbent Trike	Design #2 Rower	Design #3 Stepper Scooter	Design #4 Stabilized Bicycle
Cost	5%	2	3	3	4
Ease of Manufacturing	5%	3	1	3	3
Reliability	10%	3	2	3	4
Weight	15%	3	2	5	5
Component Space	5%	4	4	2	2
Stability	10%	4	4	3	2
Safety	10%	3	2	2	3
Sprint	10%	3	2	3	5
Endurance	10%	4	2	3	5
Efficiency	2.5%	3	2	3	4
Regeneration	2.5%	4	3	2	4
Innovation	15%	2	4	5	2
Total	100%	3.075	2.625	3.425	3.6

Selected Vehicle Design



Component Identification: Calculations



Pulling Force:

$$F_p = W \frac{\pi}{180} \sin(\theta) = 29.85 \text{ lbf}$$

Rolling Resistance:

$$F_R = W \mu_f \cos(\theta) = 5.04 \text{ lbf}$$

Total Pull Required:

$$F_{total} = F_R + F_p = 34.89 \text{ lbf}$$

Gear Ratio:

$$72:9 = 8:1$$

Torque:

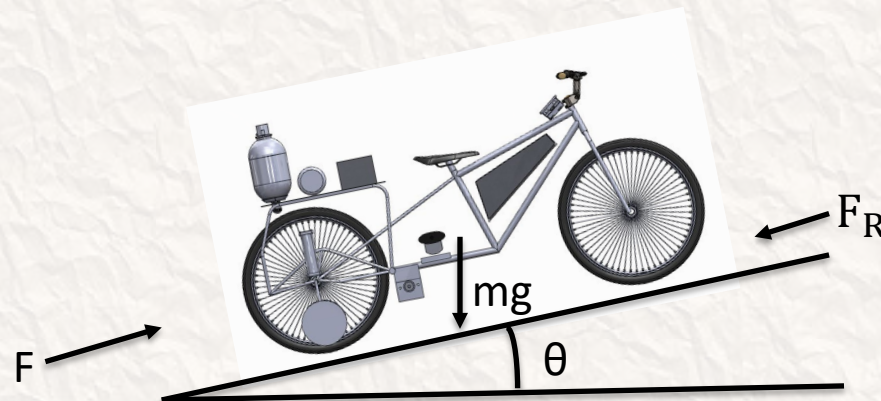
$$\tau = F_{total} R = 453.62 \text{ in} \cdot \text{lb}$$

CIR motor:

$$CIR_{motor} = 2\pi \frac{\tau}{1000} = 0.193 \text{ in}^3/\text{rev}$$

CIR of Pump:

$$CIR_{motor,act} = \frac{231 \text{ GPM}}{\text{RPM}} \eta_{pump} = 0.066 \text{ in}^3/\text{rev}$$



Components: Hydraulics

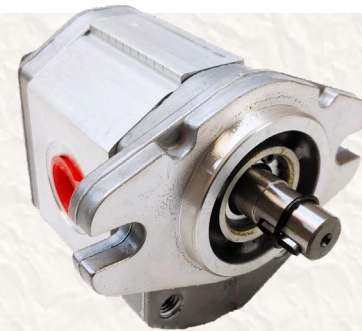
Pump

- *Dynamic* Aluminum Gear Pump
- GP-F10-13-P-C
- 0.0854 in³/rev



Motor

- *Marzocchi* Bidirectional Gear Motor
- ALM1A-R-5-E2
- 0.2135 in³/rev



Accumulator

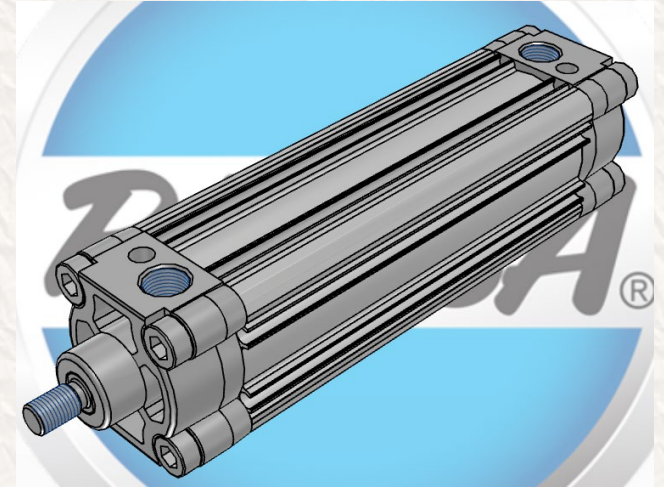
- *SteelHead* Composite Accumulator
- AB30CND10G0N
- 1 gallon



Components: Pneumatics

Cylinder

- NFPA Actuator
- PA-MS4-2.00X6-HC-KK1-MPR
- 2" Bore, 6" Stroke



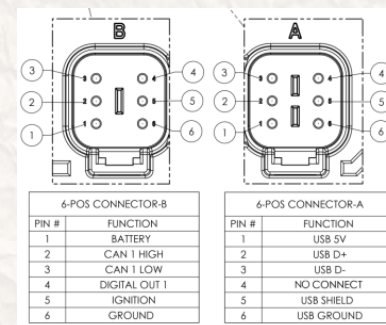
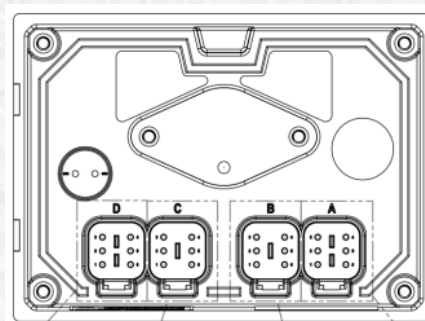
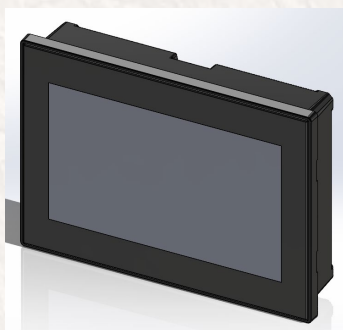
Air Reservoir

- Steel Compressed Gas Tank
- CRVZS-2
- 2 Liter



Components: Electronics

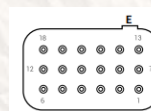
Interface: Enovation Power Vision 500



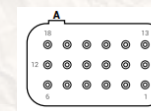
Controller: uControl Module



Inputs		MC2-18-6
Universal Analog / High Frequency		4
Universal Analog		14
TOTAL INPUTS		18
Outputs		MC2-18-6
4A PWM (feedback)		2
Dual Range PWM 4A / 0.4 A (feedback)		4
15A PWM (feedback)		0
TOTAL OUTPUTS		6
Other		MC2-18-6
CAN		2
Sensor Supply		1



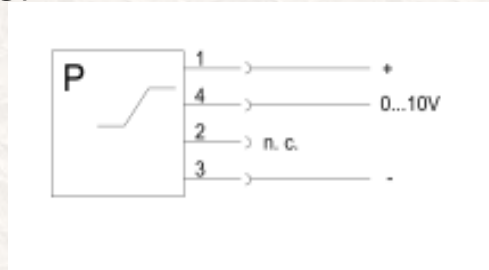
Connector J1 Key E	
Pin	Function
E1	Power Battery (+)
E2	Output PWM 4A With Feedback
E3	Output PWM 4A With Feedback
E4	Input Universal Analog
E5	Load Power (+)
E6	Battery Ground (-)
E7	Sleep Mode
E8	Output PWM Dual Range 4A / 0.5A
E9	Output PWM Dual Range 4A / 0.5A
E10	Input Universal Analog
E11	Load Power (+)
E12	Battery Ground (-)
E13	Output PWM Dual Range 4A / 0.5A
E14	Output PWM Dual Range 4A / 0.5A
E15	Input Universal Analog
E16	Input Universal Analog
E17	Input Universal Analog
E18	Input Universal Analog



Connector J2 Key A	
Pin	Function
A1	Sensor Supply Output (+10V/+5V)
A2	CAN2 H / RS232 TX
A3	CAN1 H
A4	Input Universal Analog
A5	Input Universal Analog
A6	Input Universal Analog
A7	Input Universal Analog / High Freq.
A8	CAN2 L / RS232 RX
A9	CAN1 L
A10	Input Universal Analog / High Freq.
A11	Input Universal Analog / High Freq.
A12	Input Universal Analog / High Freq.
A13	Sensor Supply Ground (-) / RS232 GND
A14	Input Universal Analog
A15	Input Universal Analog
A16	Input Universal Analog
A17	Input Universal Analog
A18	Input Universal Analog

Electrical Schematic

Pressure Transducer



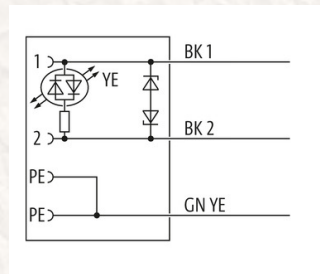
Input Channel:

Transducer 1 – A15

Transducer 2 – A16

Transducer 3 (pneumatic) – A17

Solenoid Valves



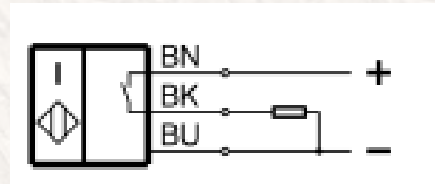
Output Channel:

DMDA Solenoid – E2

DTBF Solenoid – E3

Pneumatic Solenoid (Position 1) – E8
 (Position 2) – E9

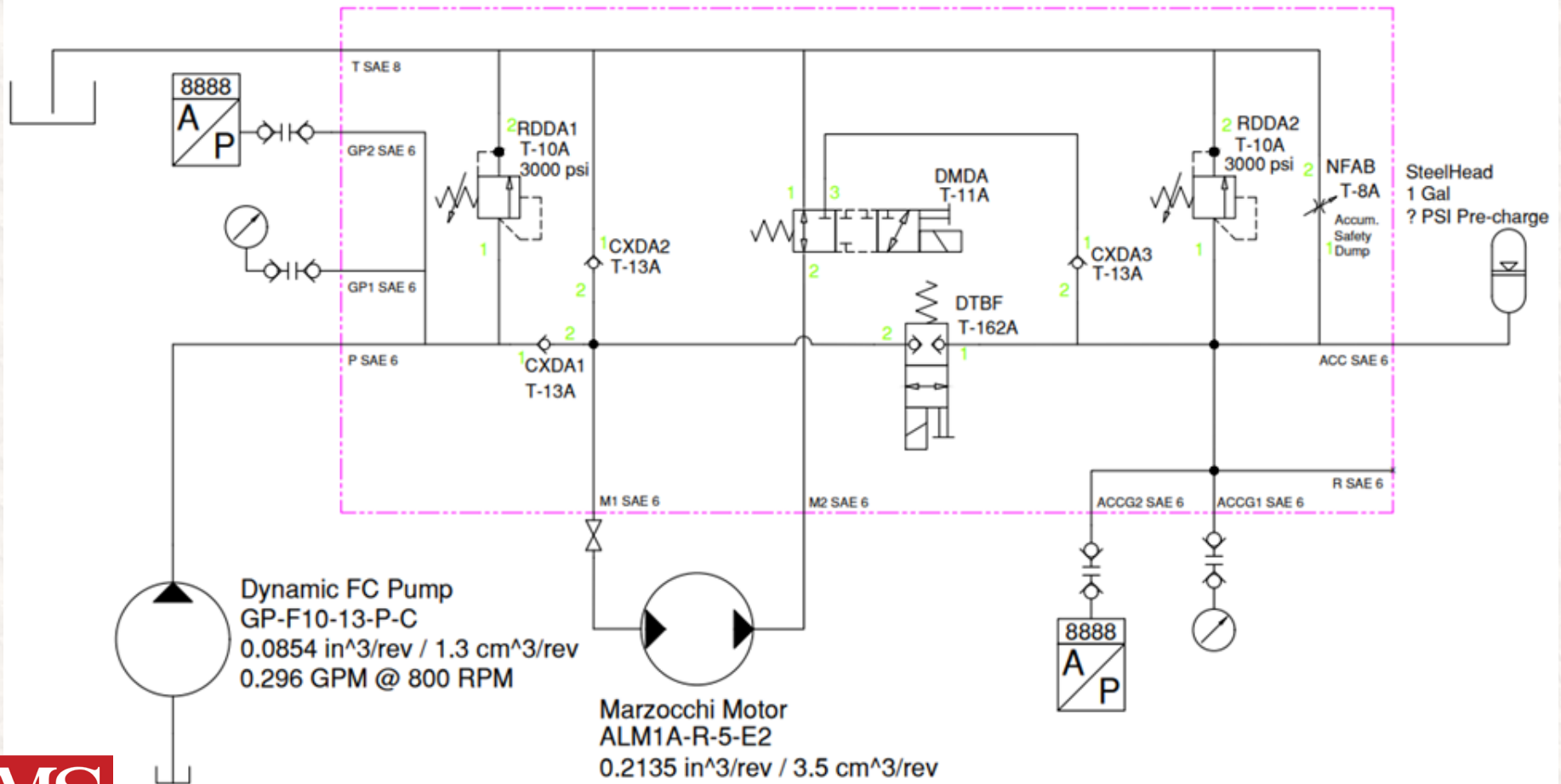
Inductive Sensor (speed)



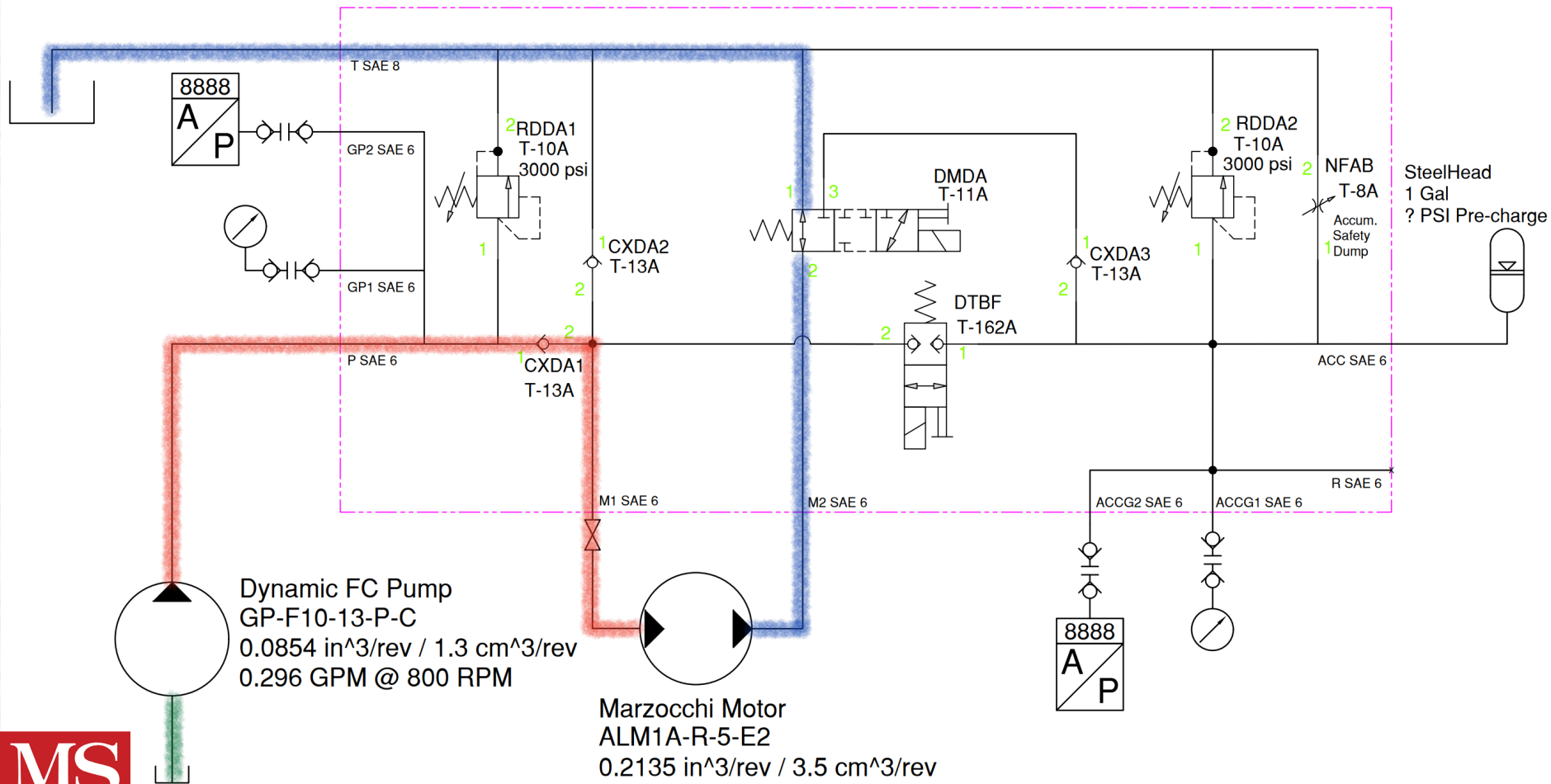
Input Channel:

Inductive Sensor – A10

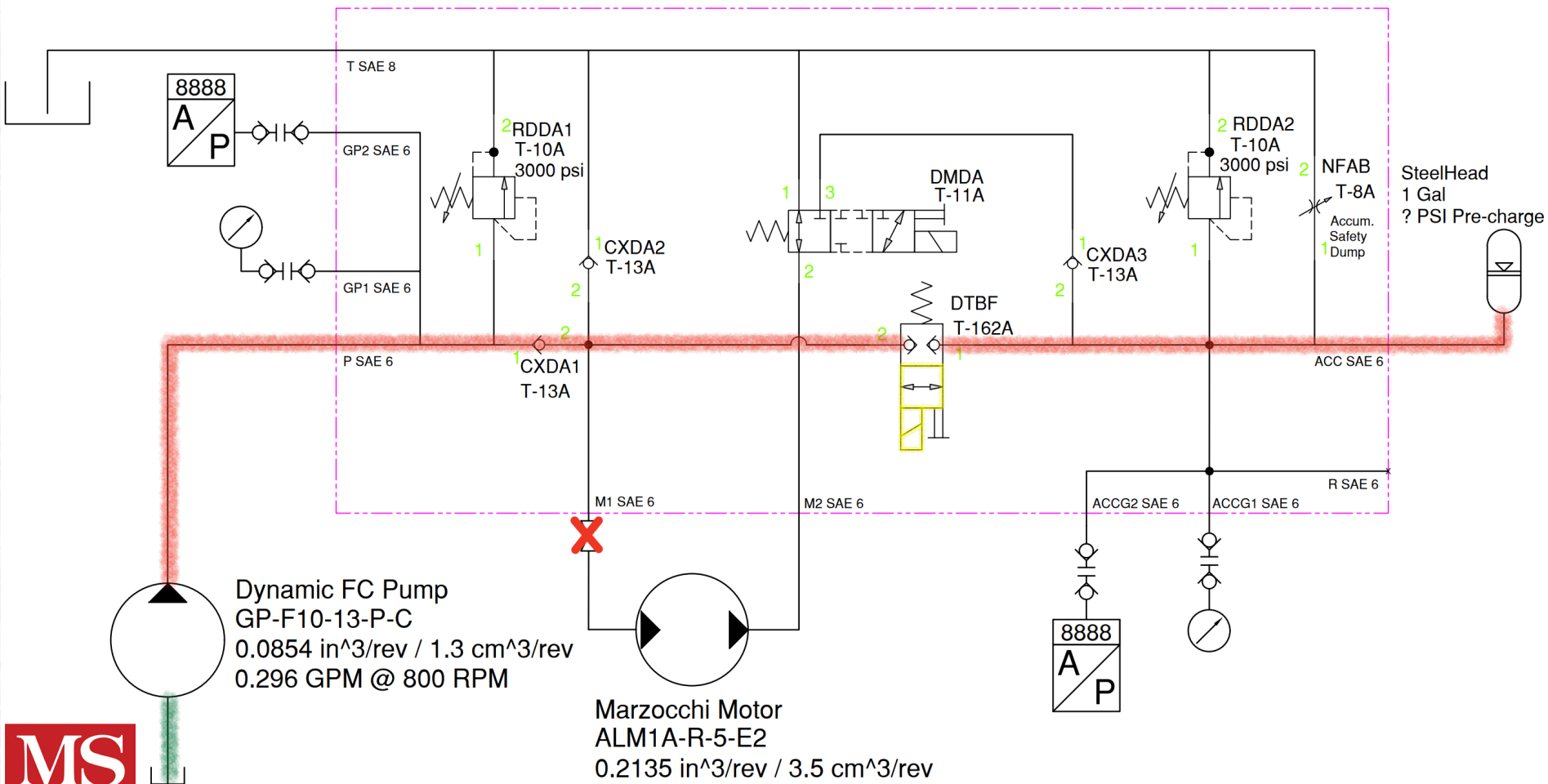
Hydraulic Circuit



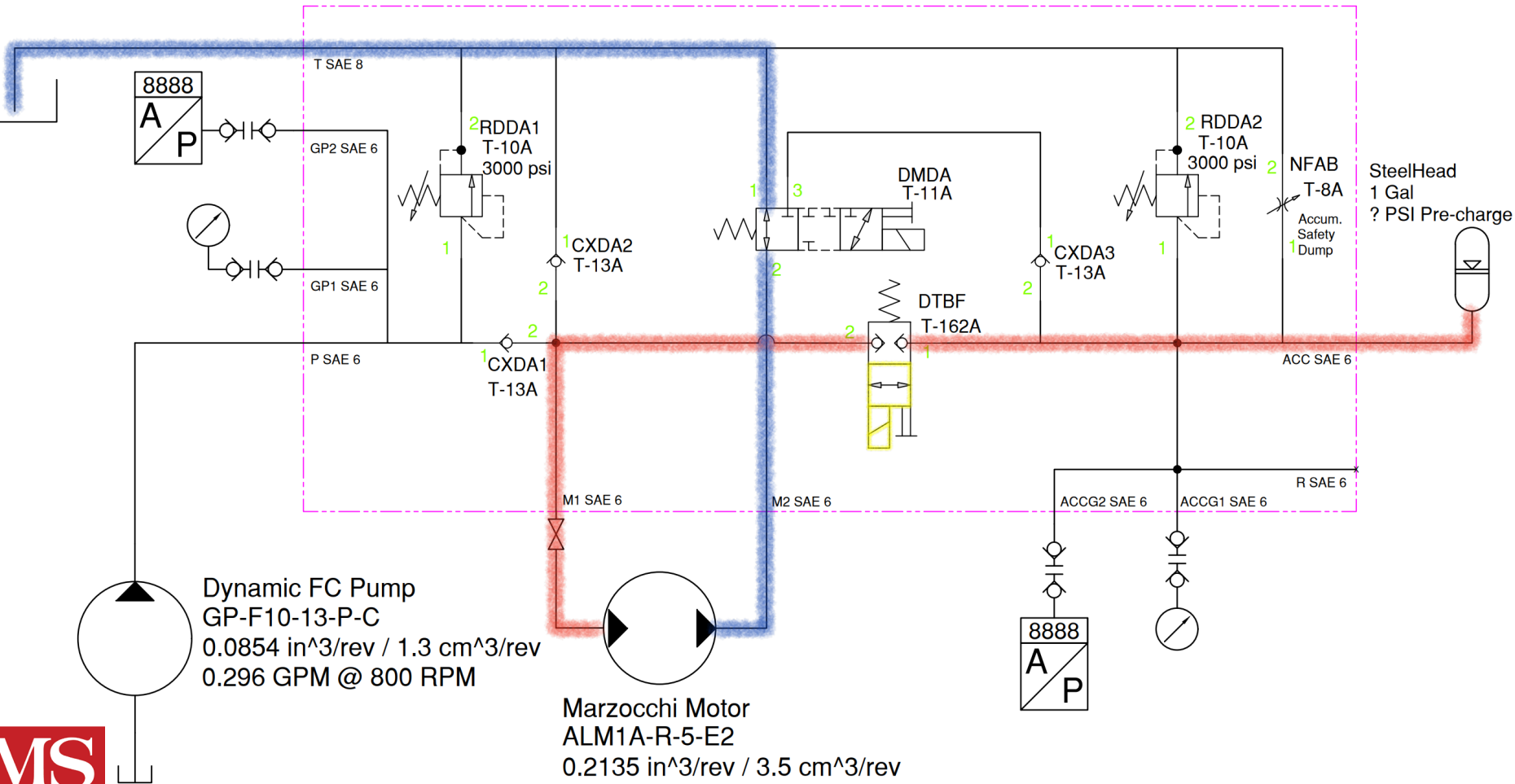
Hydraulic Circuit: Normal Drive



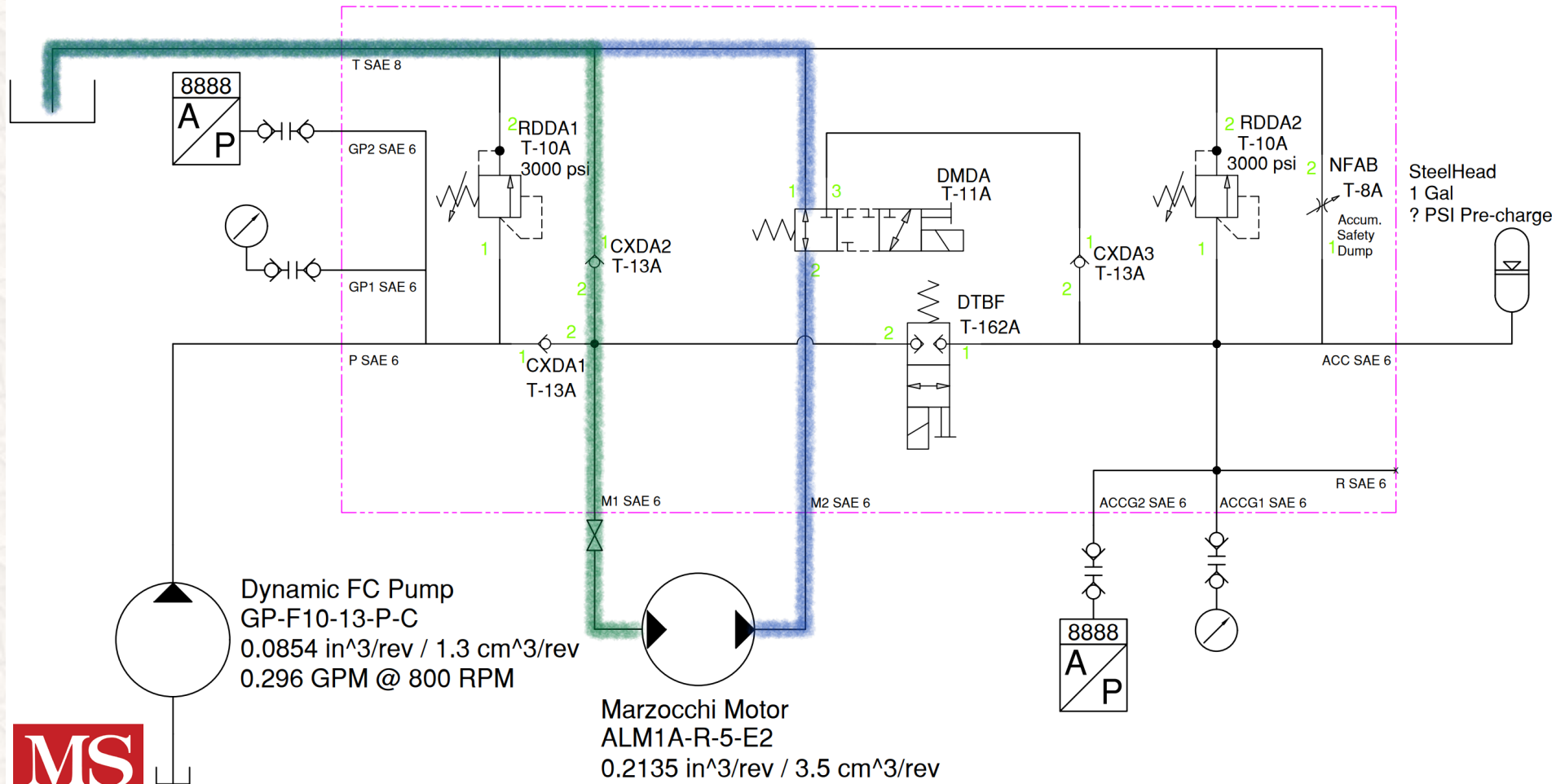
Hydraulic Circuit: Static Accumulator Charge



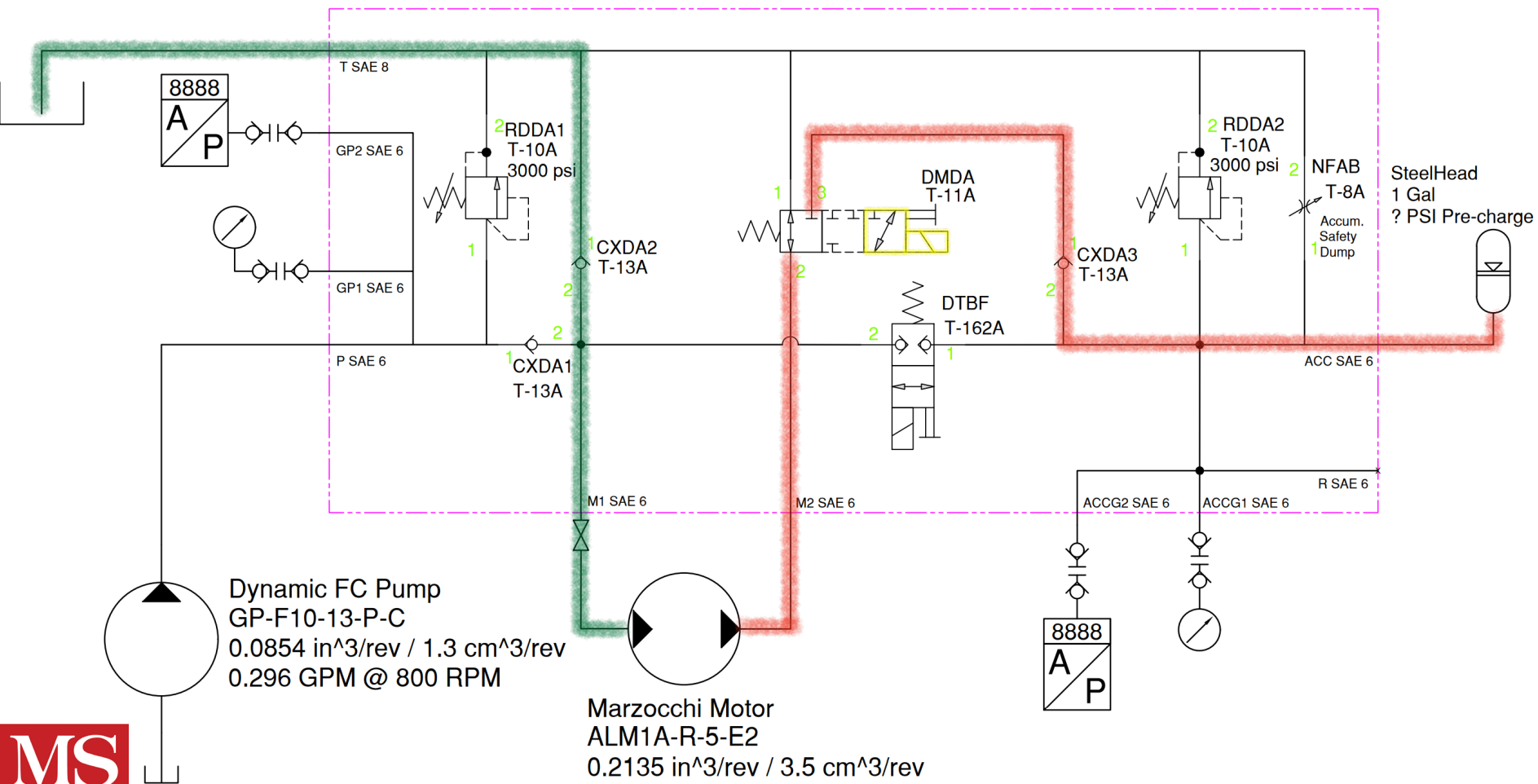
Hydraulic Circuit: Accumulator Discharge



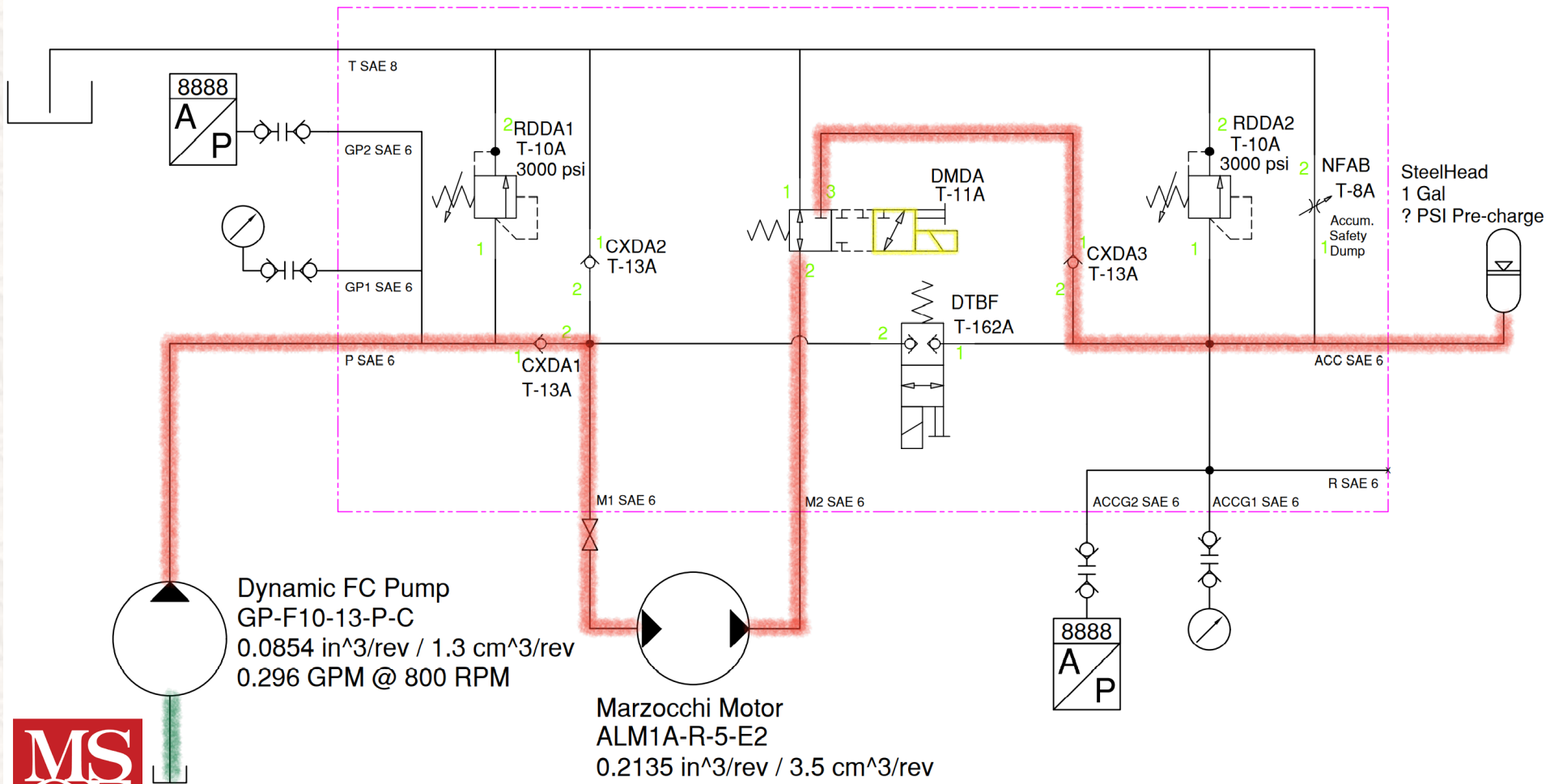
Hydraulic Circuit: Freewheeling (Default)



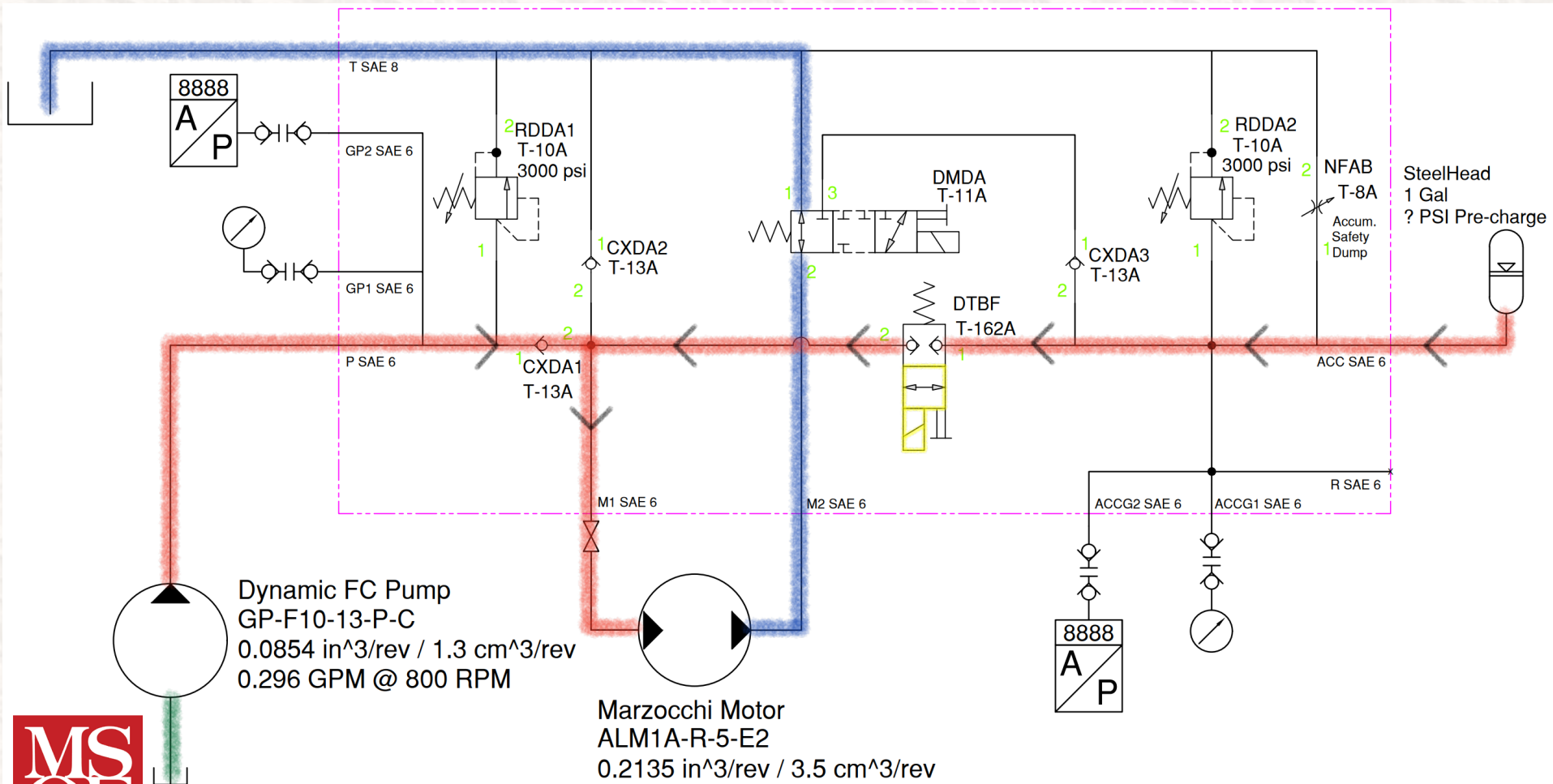
Hydraulic Circuit: Regen Brake Engaged (Freewheeling)



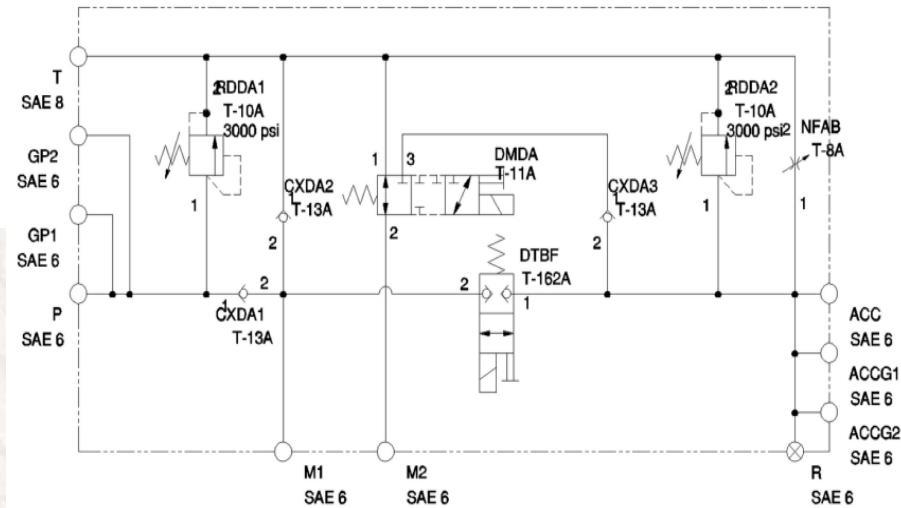
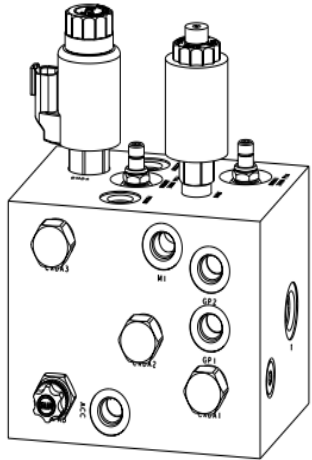
Hydraulic Circuit: Regen Brake Engaged (Pedaling)



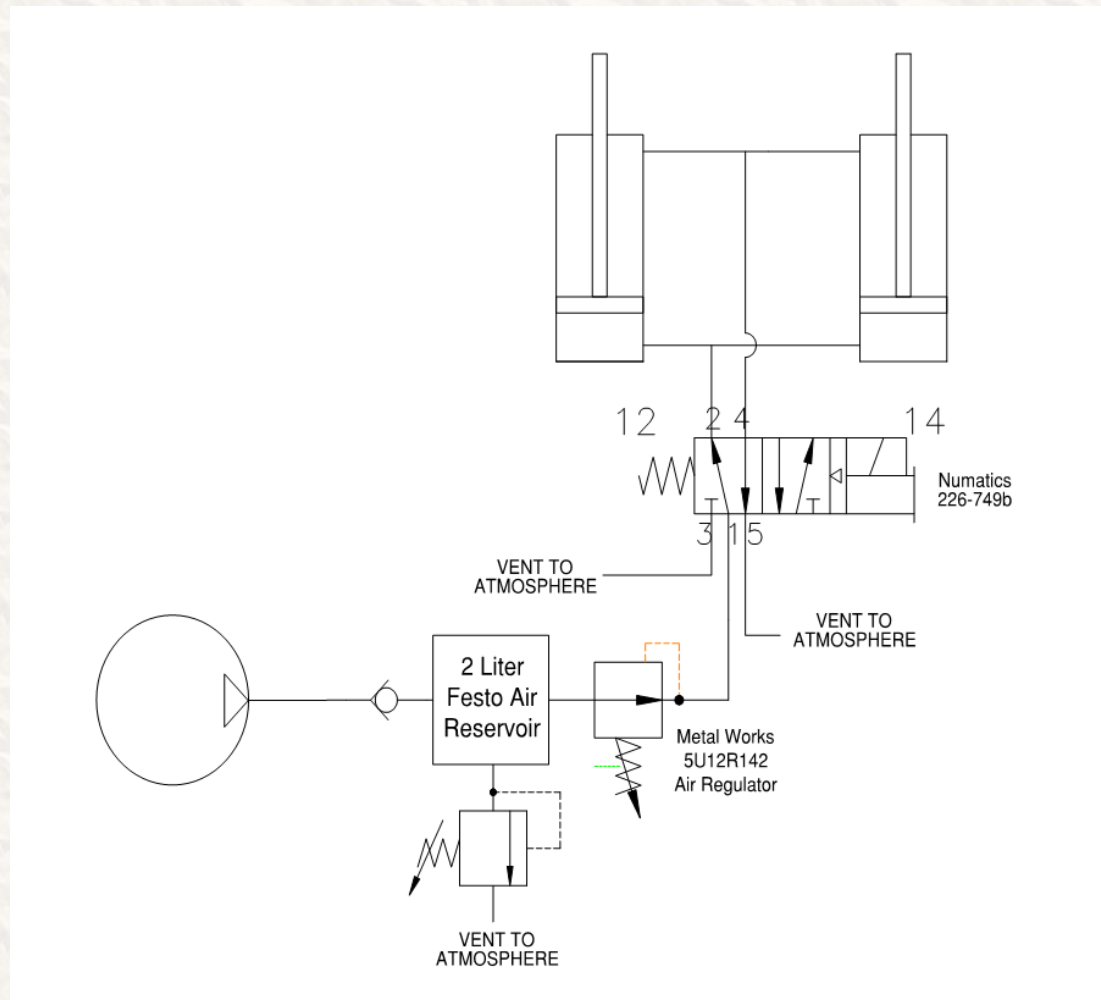
Hydraulic Circuit: Supplemented Pump Flow



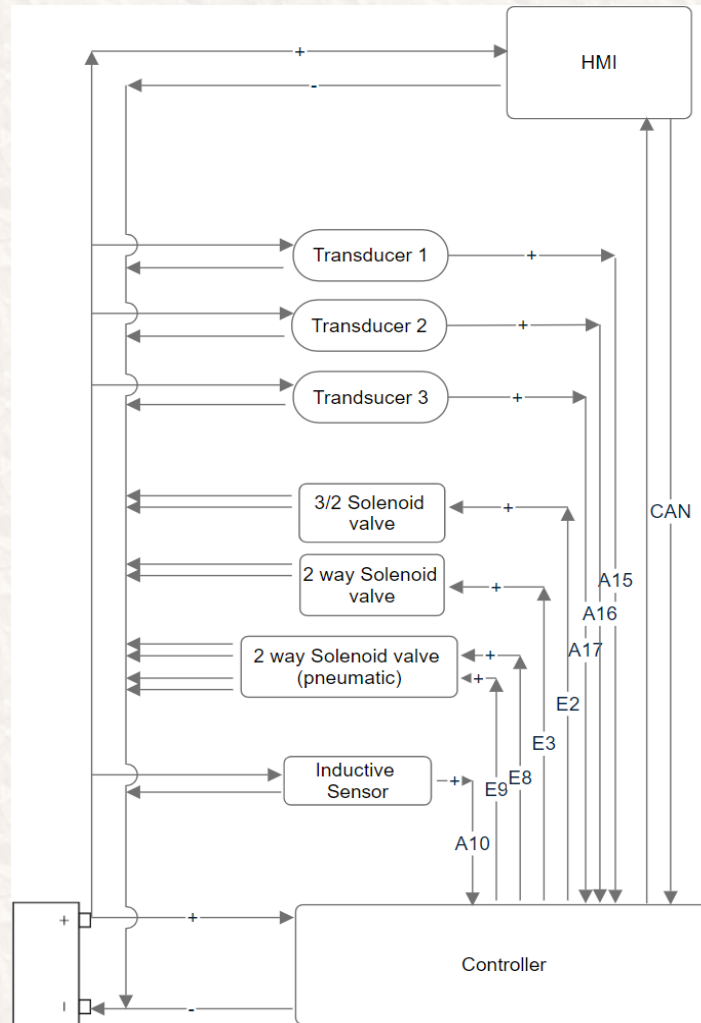
Manifold Design



Pneumatic Circuit

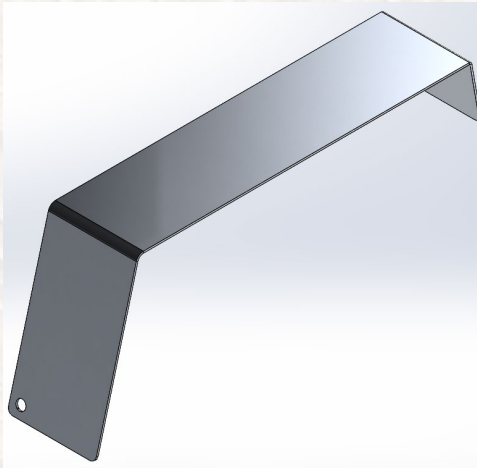


Electric Circuit

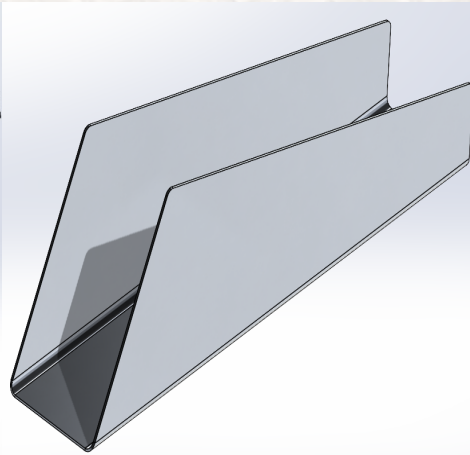


Fabrication - Reservoir

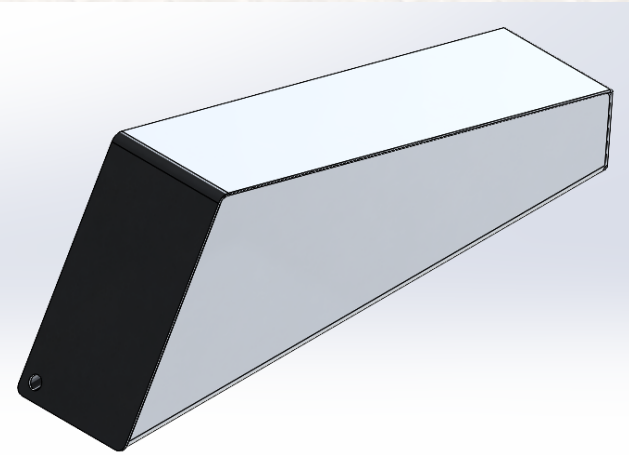
Top



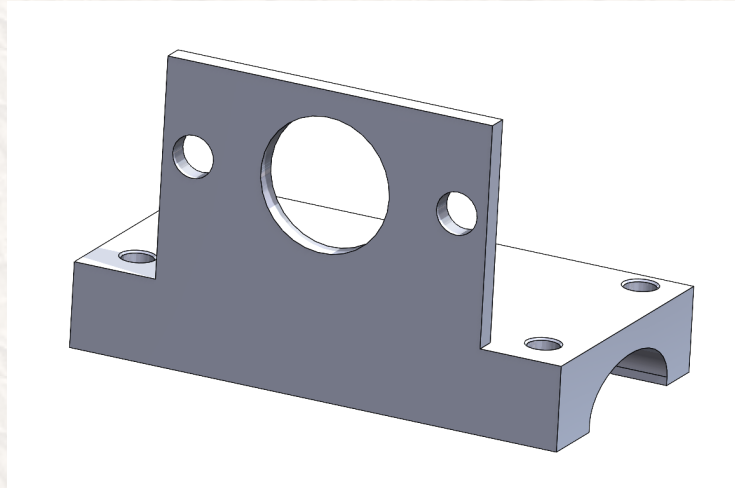
Bottom



Assembly



Fabrication – Mounts



Fabrication – Sprockets

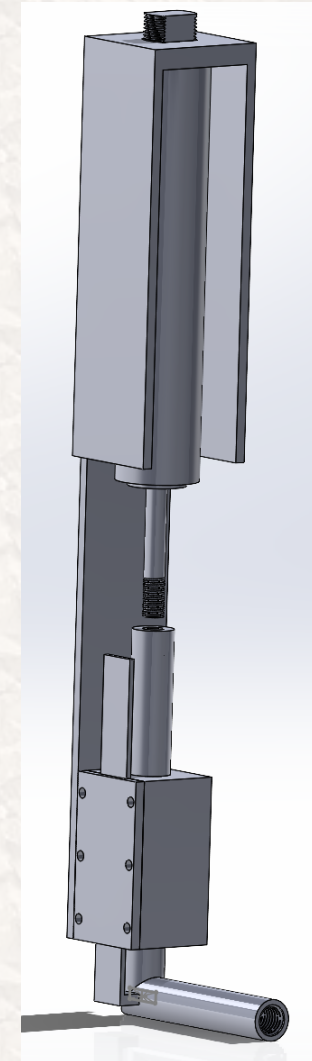
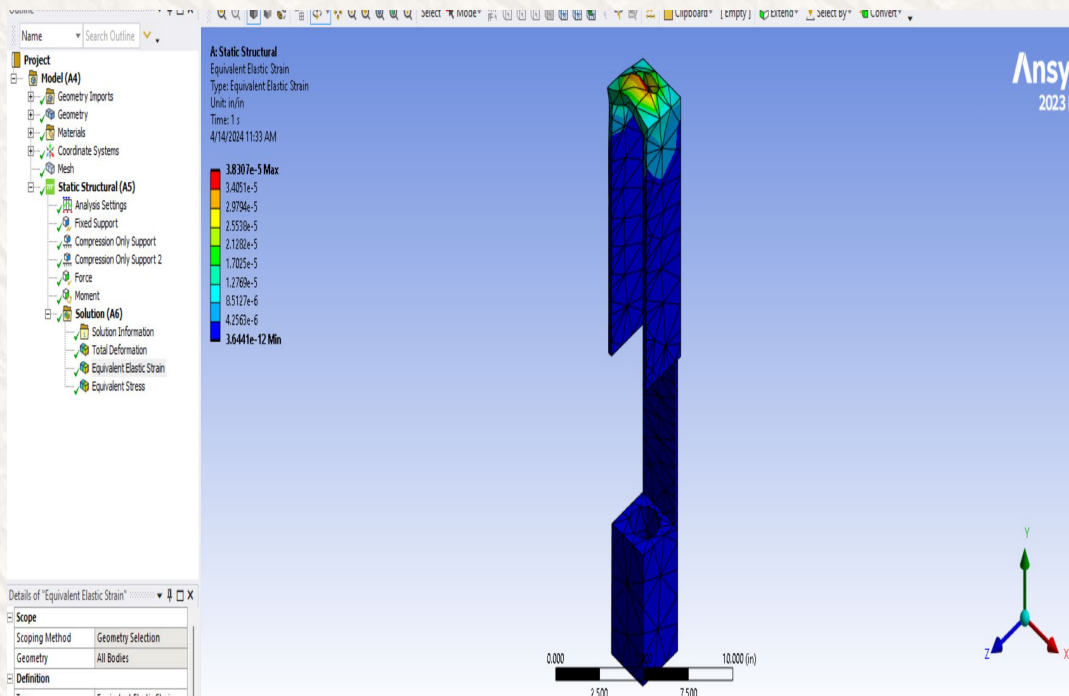


Fabrication – Bracket



Fabrication - Stabilizers

- Finite Element Analysis
- SolidWorks planning



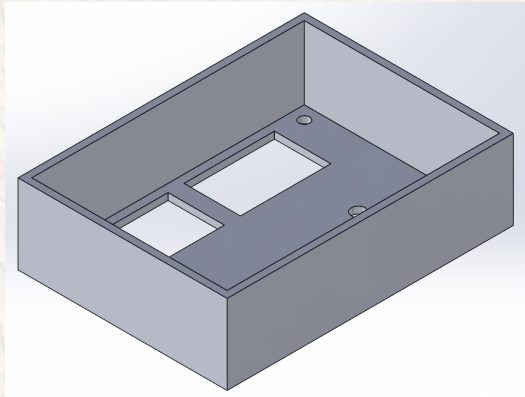
Fabrication - Stabilizers

- Stability for low speeds
- Linear movement

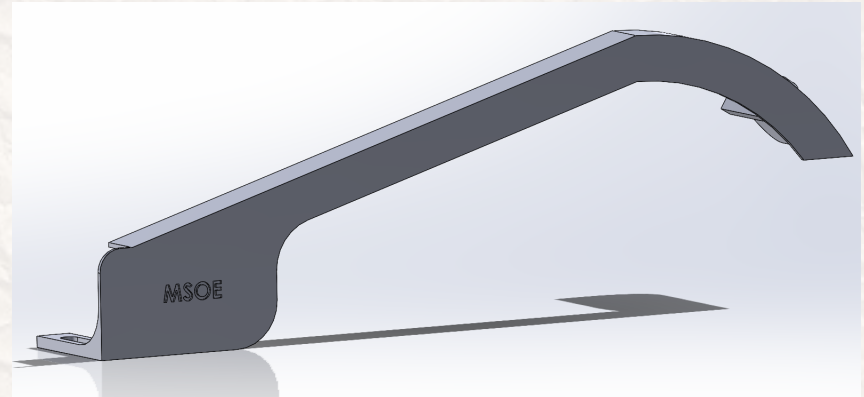


Fabrication – 3D Prints

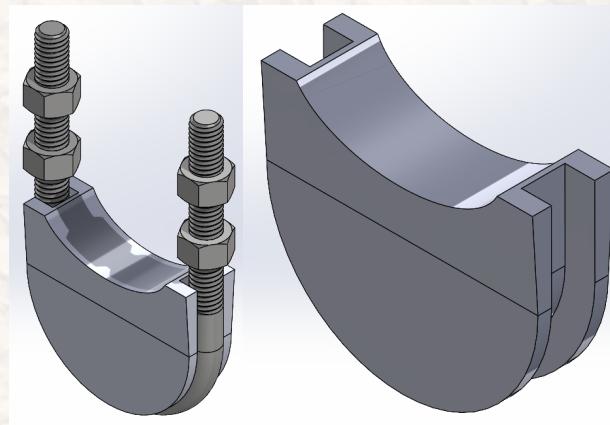
Interface Box



Chain Guard



Pump Mount Spacer



Testing Problems

- Chain issues
- Leaking connections
- Pneumatic regulator pressure



Lessons Learned

- Experience drives problem solving
- Persistence is key
- Learning is continuous



Acknowledgements



Dr. Luis A Rodriguez
Senior Design Instructor



Brett Tarczewski
Fabrication Specialist



Other Acknowledgements:

Mary Pluta

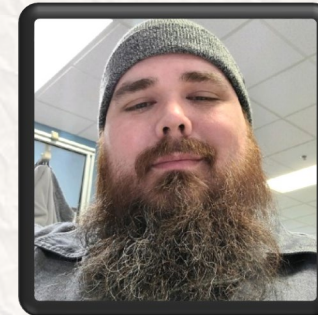
Ernie Parker, CFPAI

Dr. Kevin Hart

Various MSOE Staff

Jim Kaas, CFPE & Chandlar Armstrong, CFPHS
(MSOE '19)
Industry Mentors

Joshua Scarbrough
Controls Assistance





Questions?